

# Design and Simulation of Labyrinth Seals for Space Applications

**Josef Pouzar**

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# INTRODUCTION

## SPACE ENVIRONMENT

- Vacuum, Extreme temperatures, Radiation

## SPACE MISSIONS

- Operation over long lifetimes (5–15 years)

## MISSION-CRITICAL TRIBOLOGICAL COMPONENTS

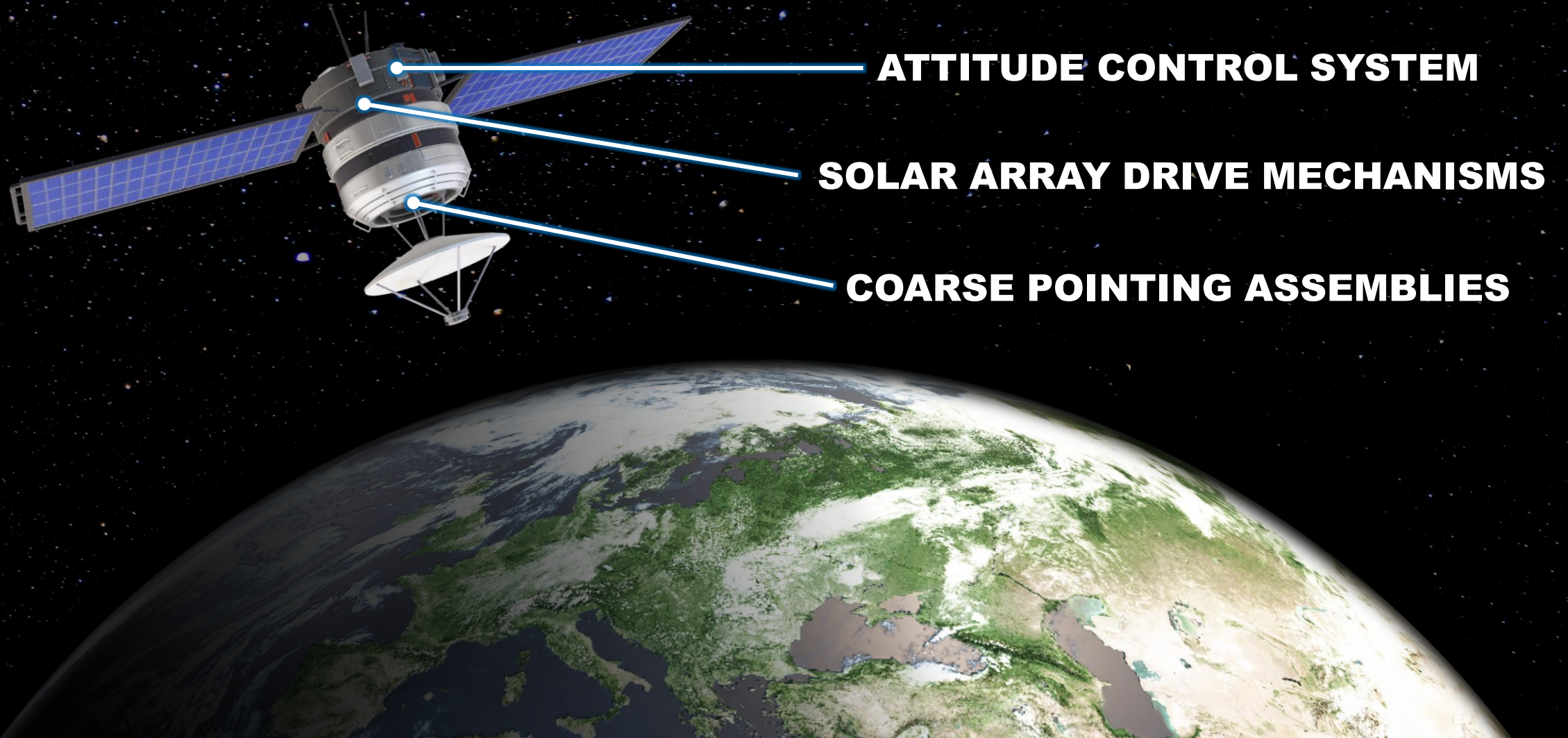
- Bearings, gears, actuators

## LUBRICATION FOR SPACE APPLICATIONS

- Solid, Fluid (oils & greases), Hybrid



# **LABYRINTH SEALS IN SPACE**



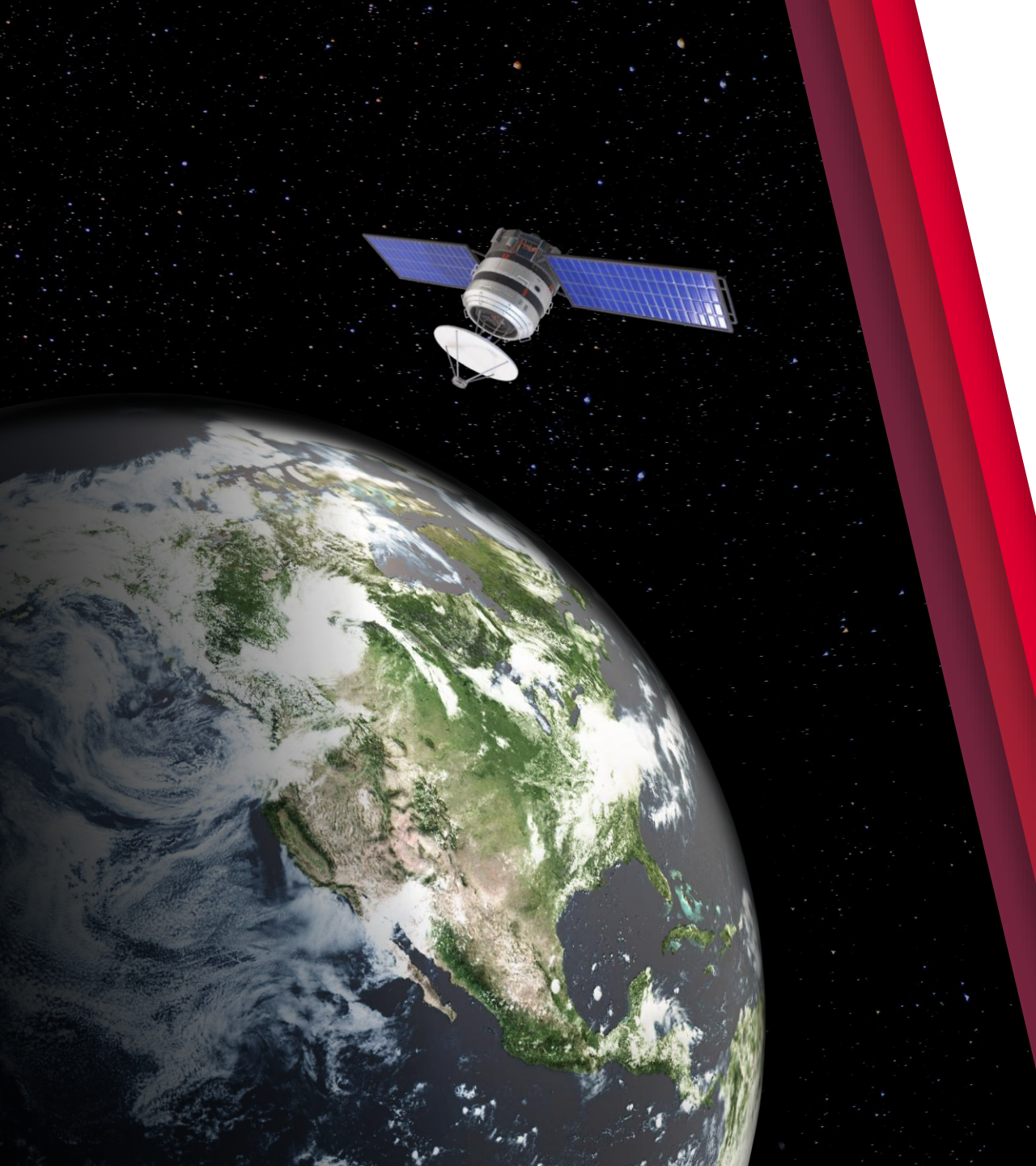
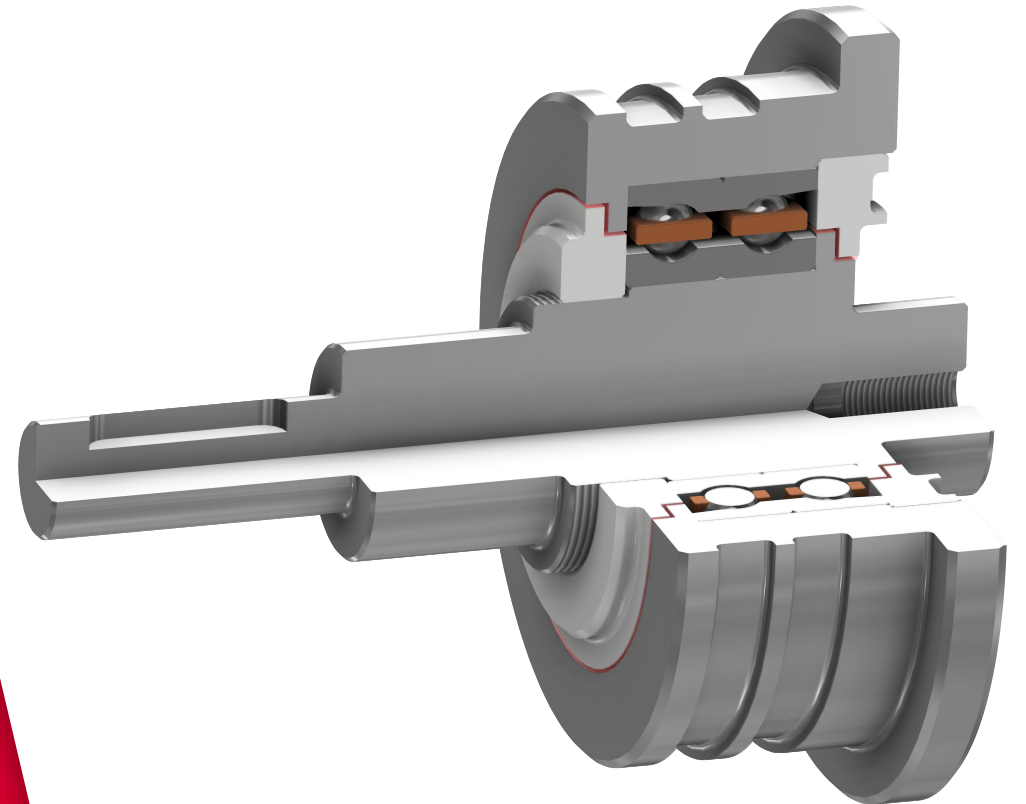
**ATTITUDE CONTROL SYSTEM**

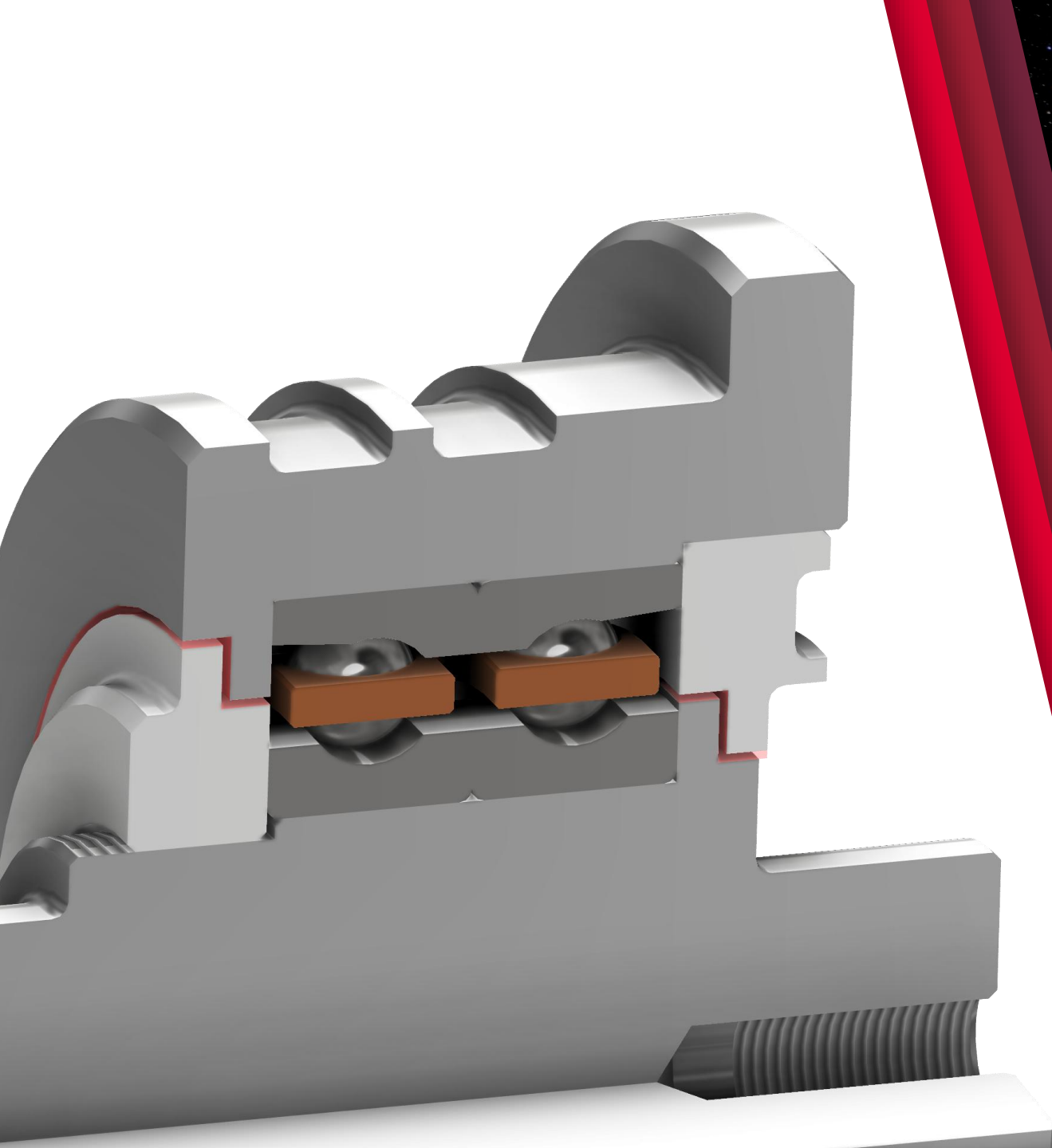
**SOLAR ARRAY DRIVE MECHANISMS**

**COARSE POINTING ASSEMBLIES**

# LABYRINTH SEALS

- **Sealing lubricant evaporation**
- **Preventing contamination**
- **Design for each assembly**





# LAYBRINTH SEAL RESEARCH AREAS

- **Overall geometry**
  - **Length, Width, Complexity**
- **Local modifications**
- **Surface topography**
- **Rotational influence**

# MOLECULAR FLOW

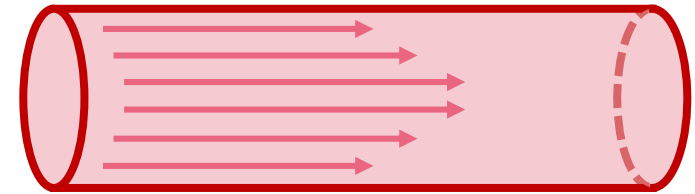
## VACUUM ENVIRONMENT (UHV, XHV)

- Molecules move freely
- Primary surface collisions
- Rare intermolecular collisions

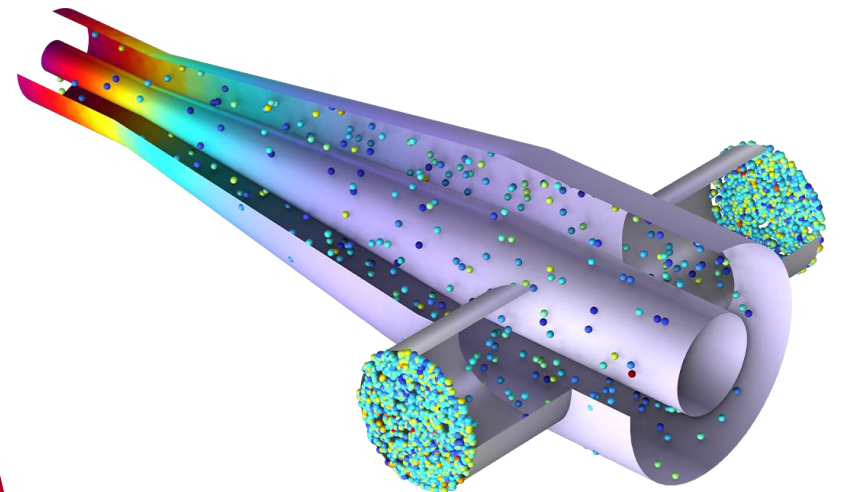
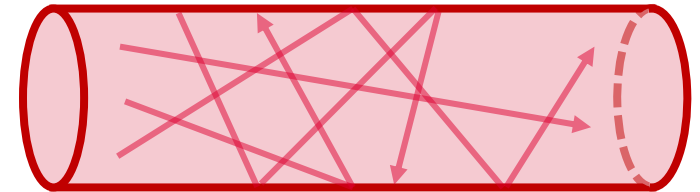
## VACUUM EVAPORATION

- Vacuum pressure  $\leq$  Vapor pressure

### Viscous flow



### Molecular flow



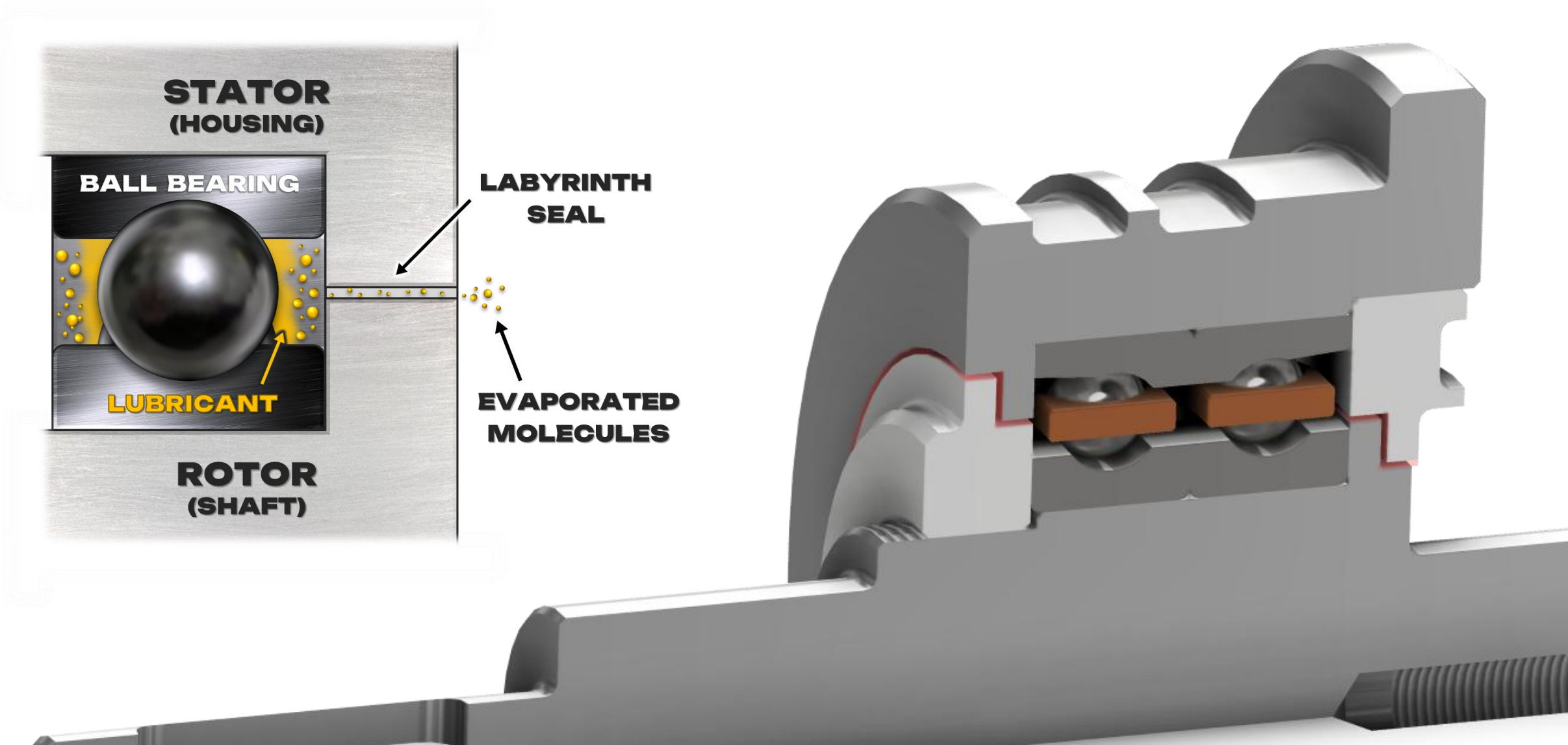
# **EVAPORATIVE MASS LOSS**

**ANALYTICAL**

**SIMULATION**

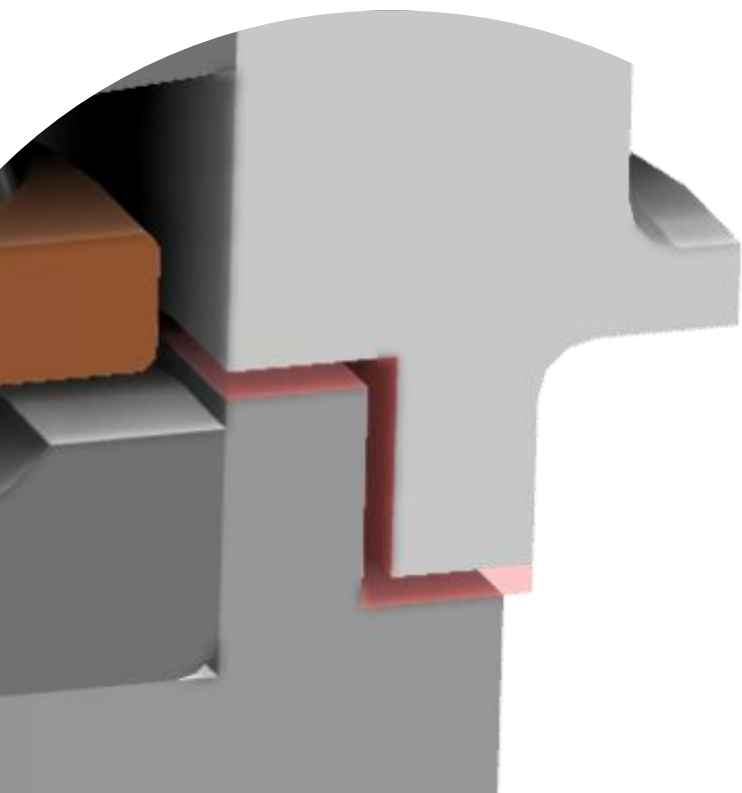
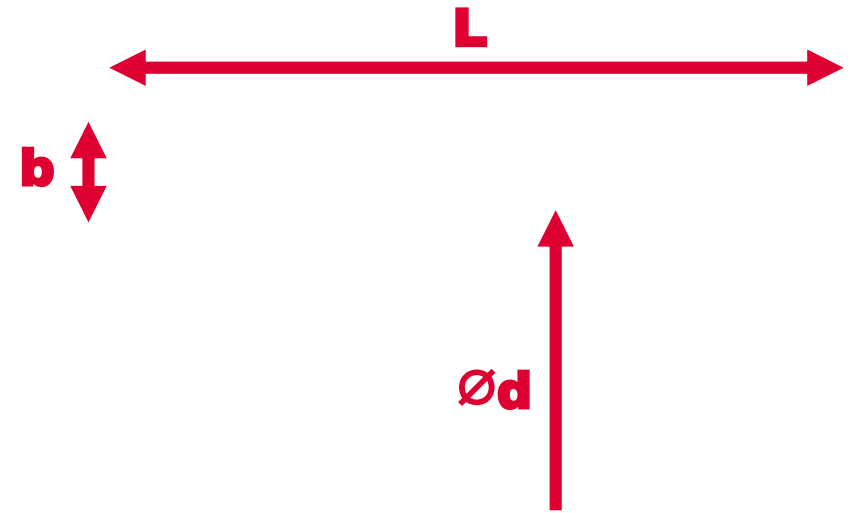
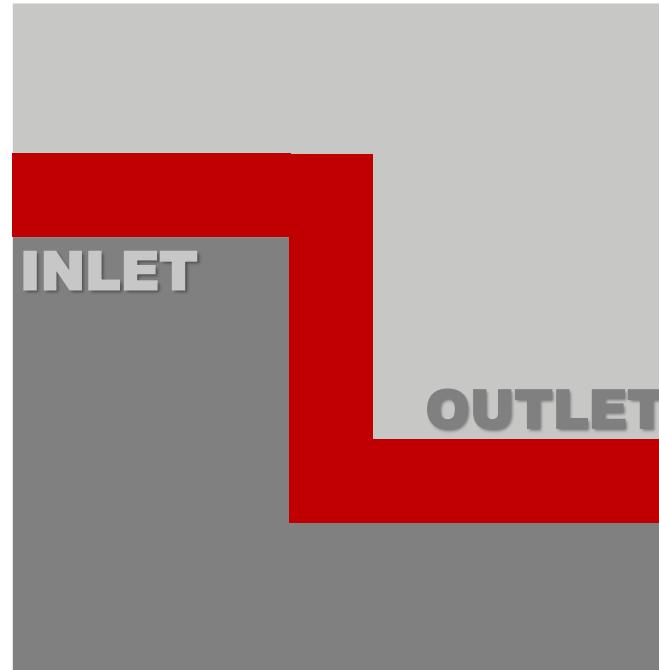
**EXPERIMENT**

# ANALYTICAL



# ANALYTICAL

MOLECULE  $\triangleright \bullet$



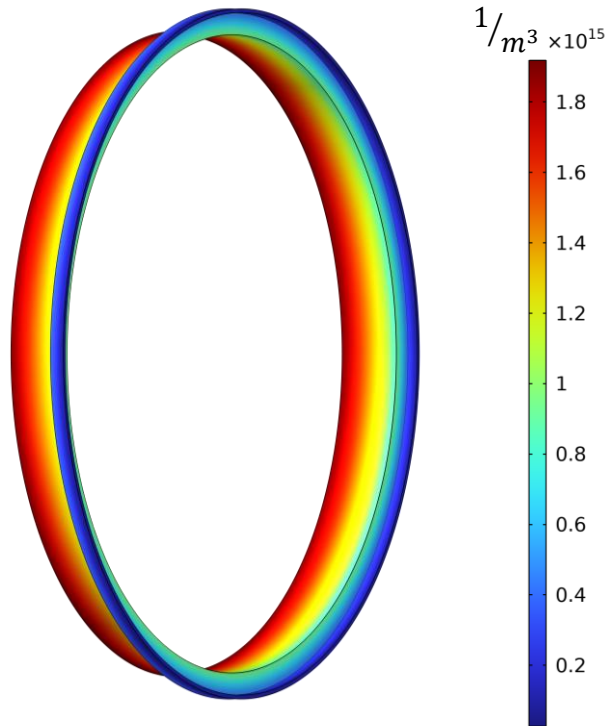
**ESTL Model:**

$$Q_m = 0,0436 \frac{P_v \pi d b \left(\frac{M}{T}\right)^{0,5}}{1 + 0,375 \cdot \frac{L}{b}} \quad [g/s]$$

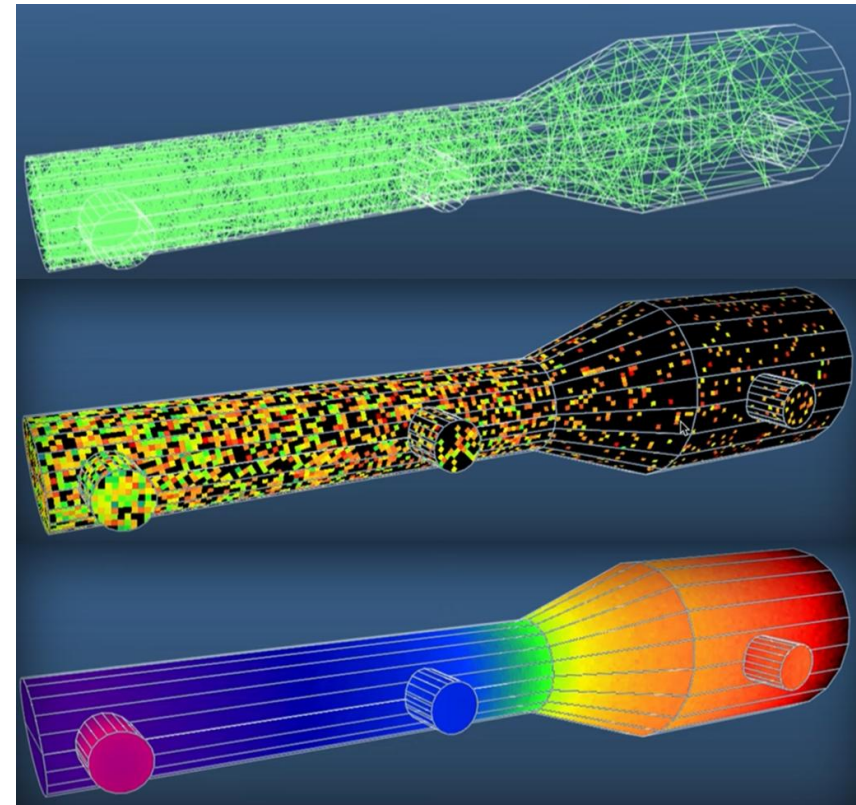
# SIMULATION

## COMSOL MULTIPHYSICS

- Particle Tracing module
- Molecular flow module

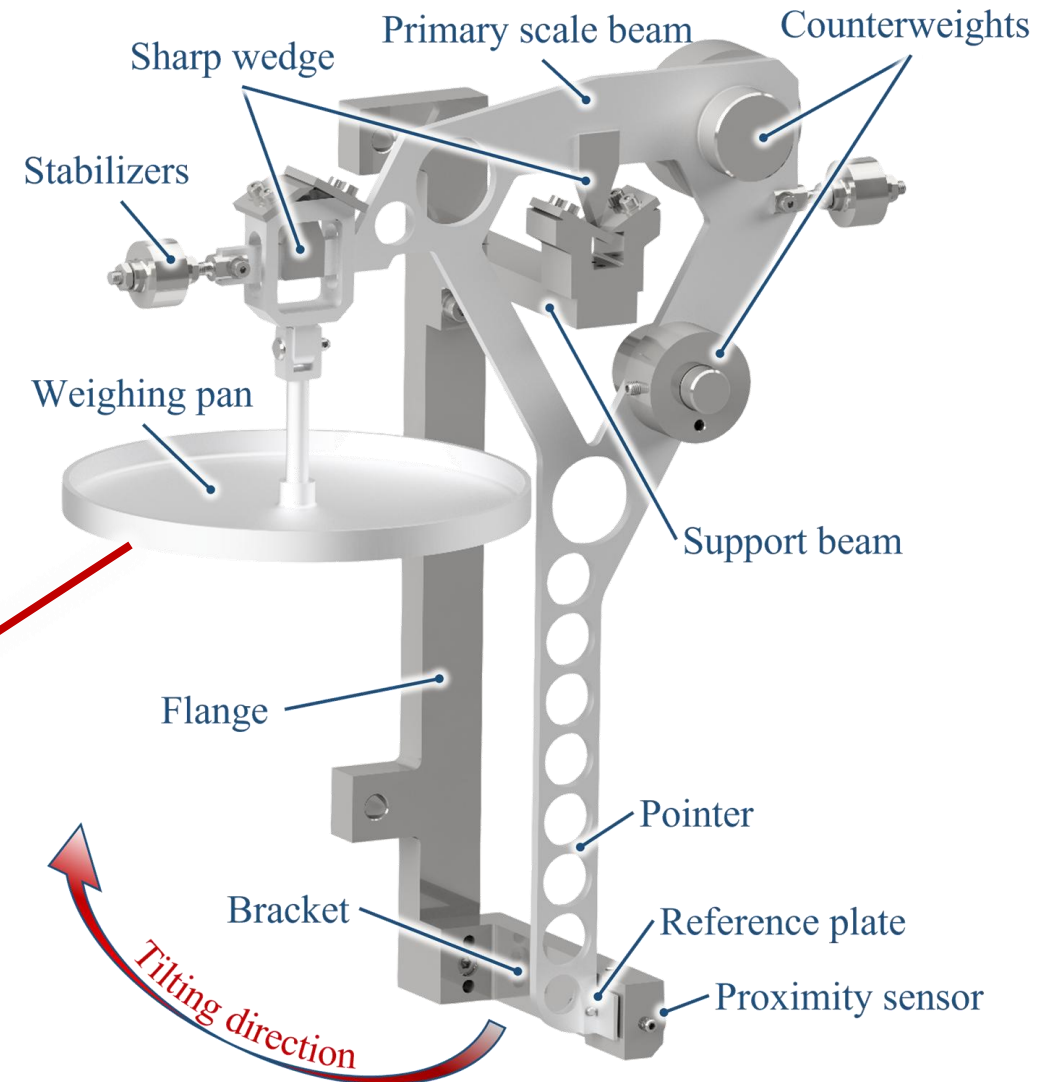


## MOLFLOW+ (CERN)



# EXPERIMENT

## EVAPORATION TEST RIG (ETR)



# **EVAPORATIVE MASS LOSS**

**ANALYTICAL**

**SIMULATION**

**EXPERIMENT**

# LABYRINTH SEAL OPTIMIZATION

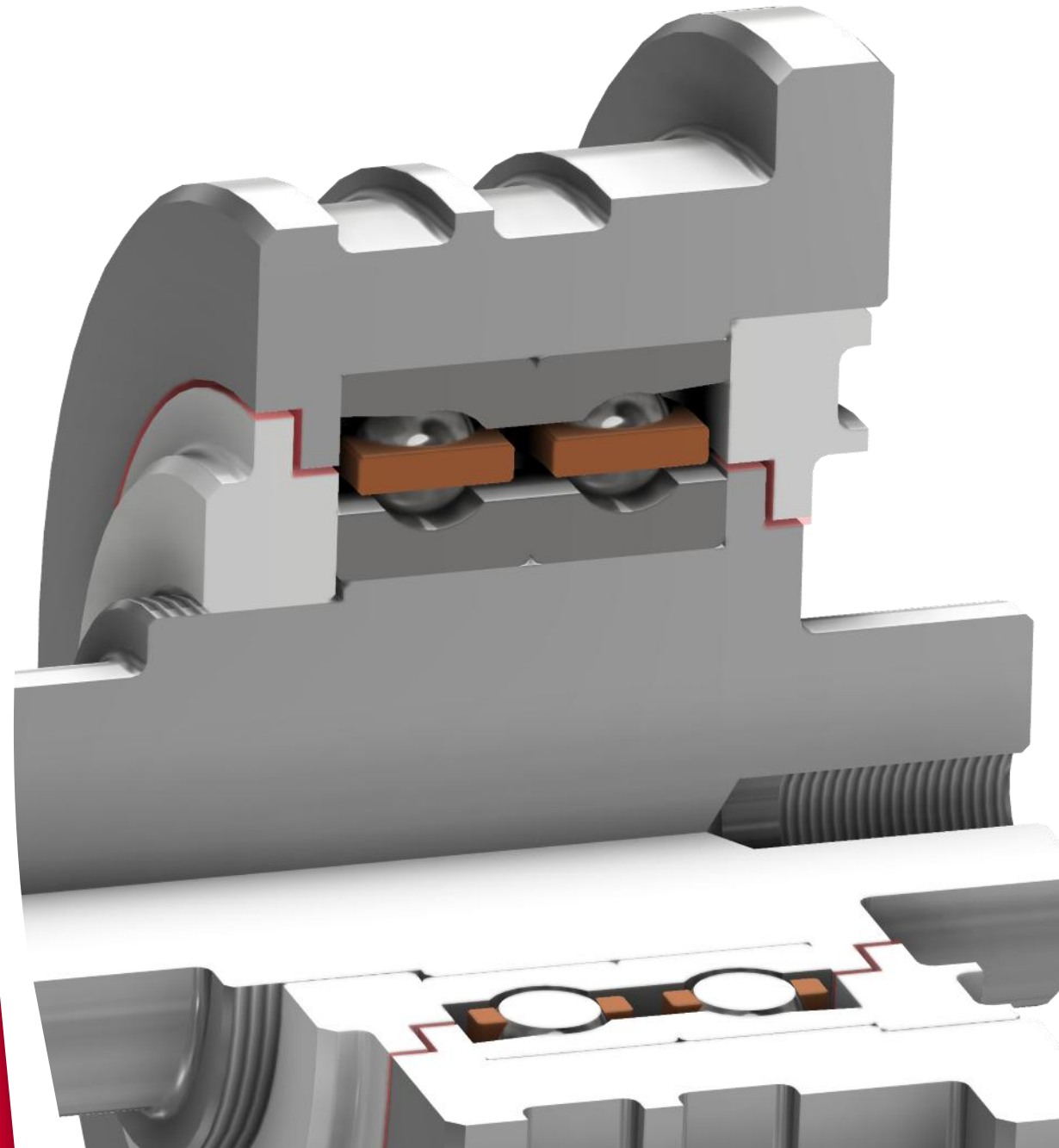
- **Overall geometry**

Length, Width, Complexity

- **Geometrical modifications**

- **Surface topography**

- **Rotational influence**



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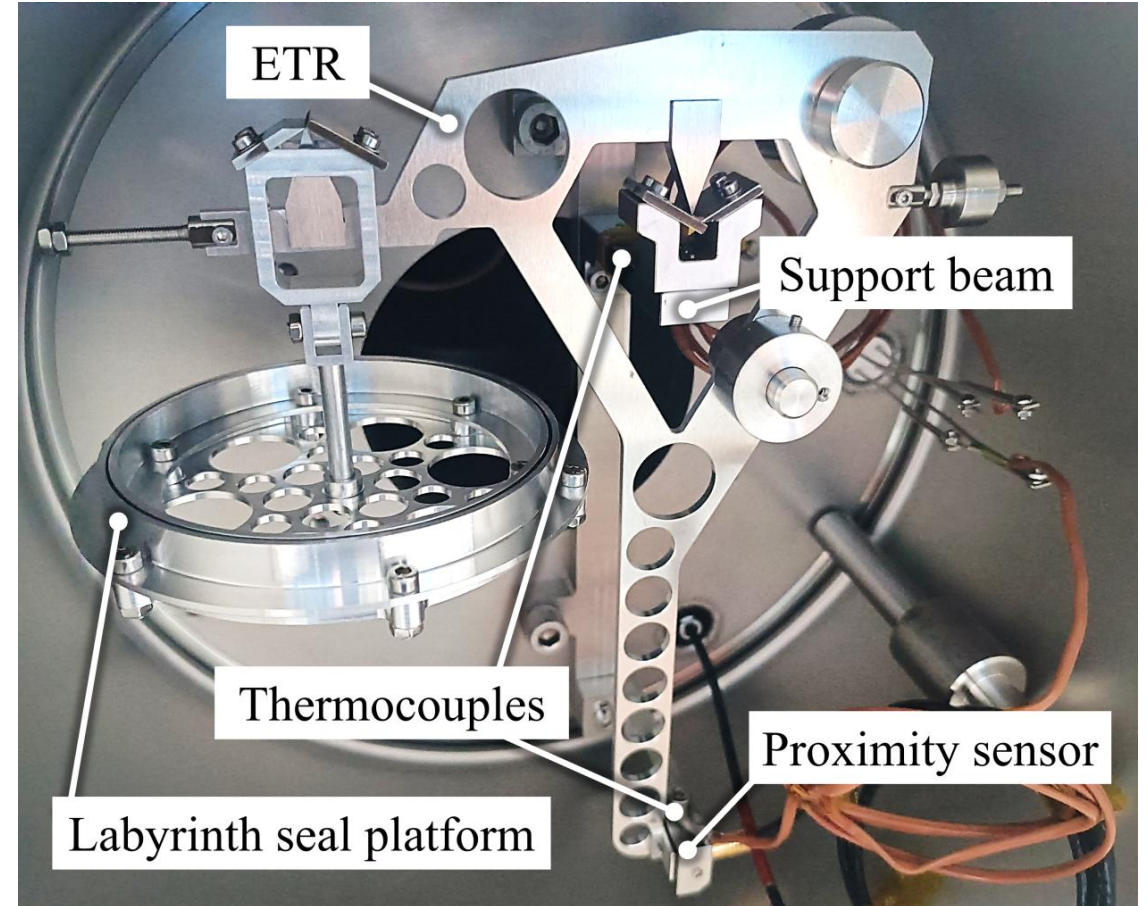
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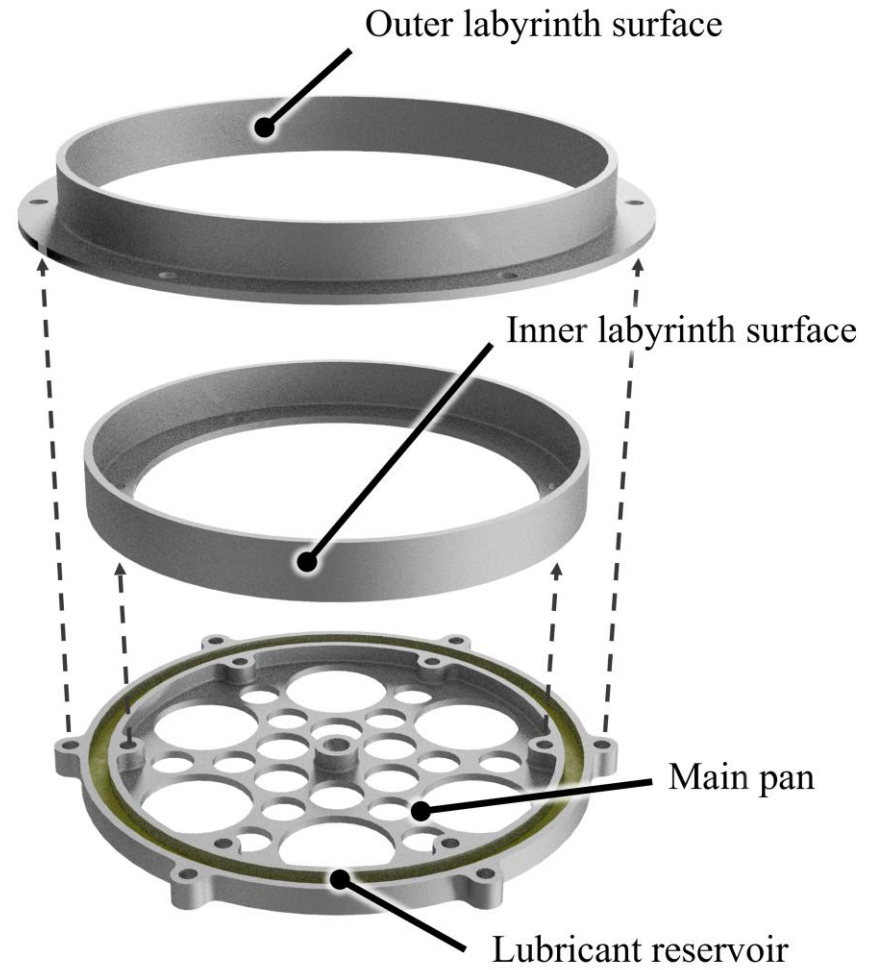
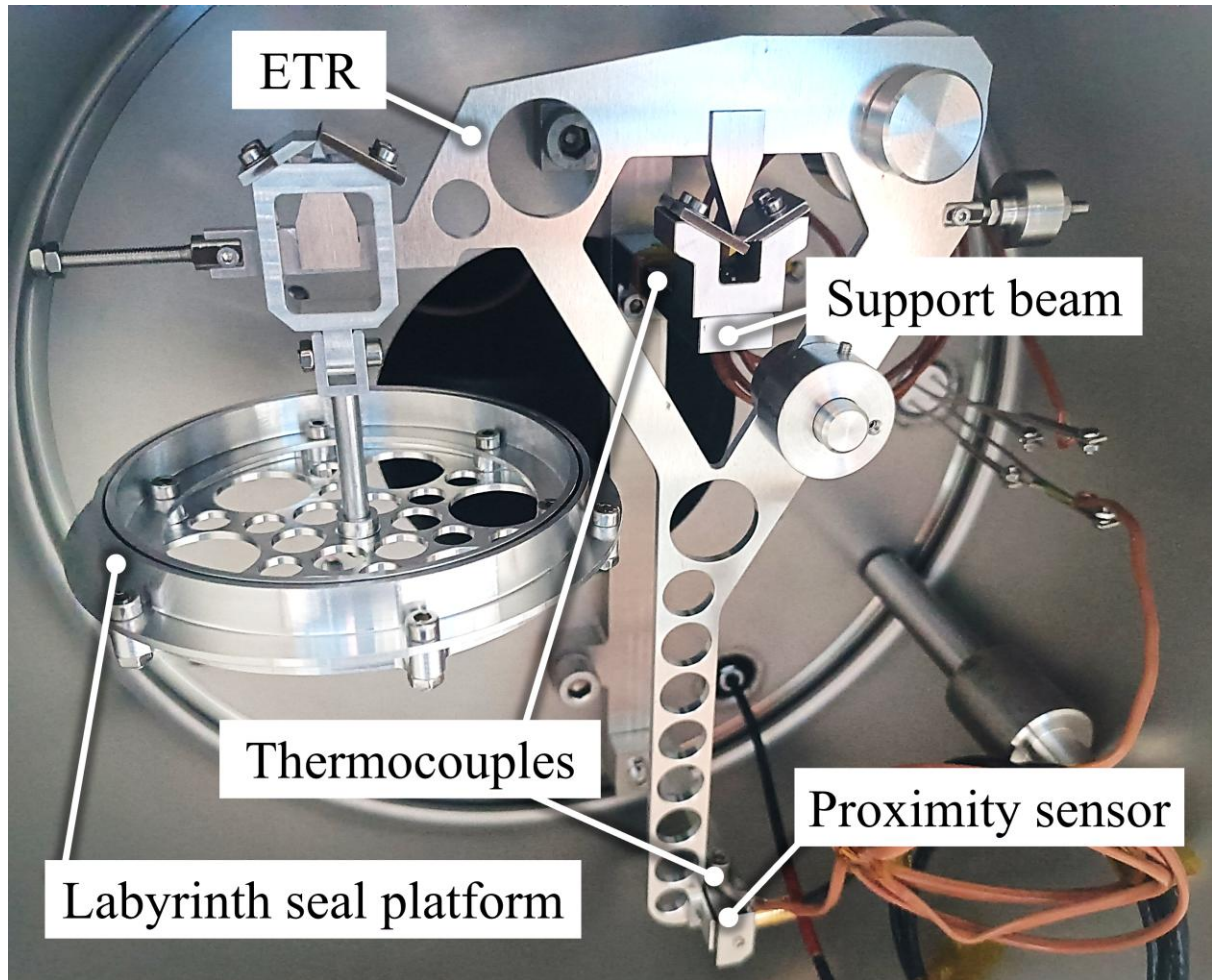
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- **Geometrical modifications**

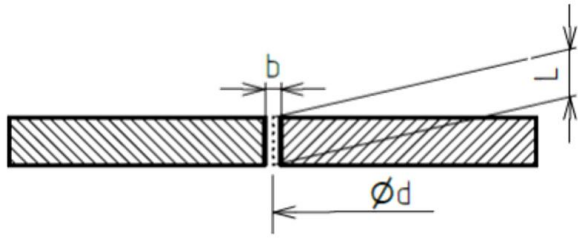
- **Surface topography**

- **Rotational influence**

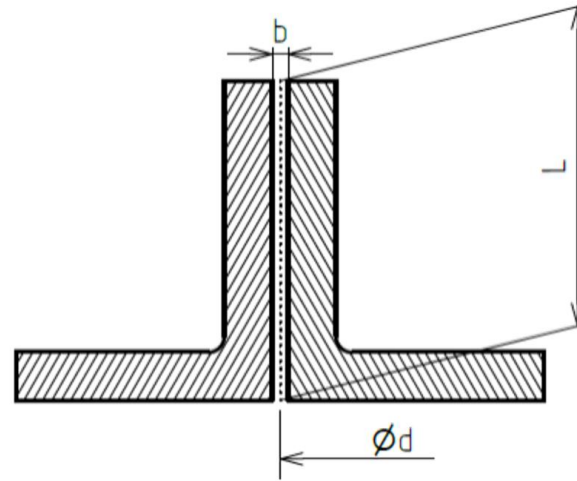




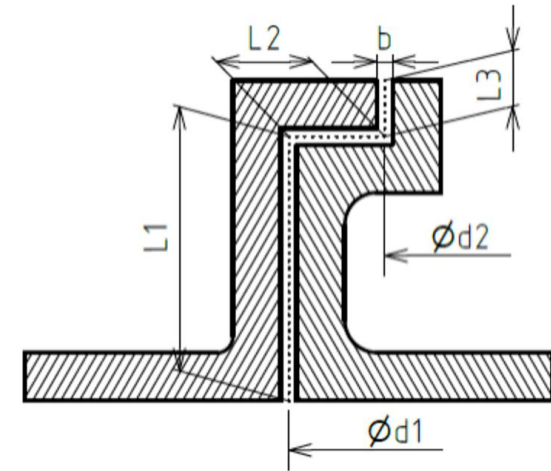
## SHORT



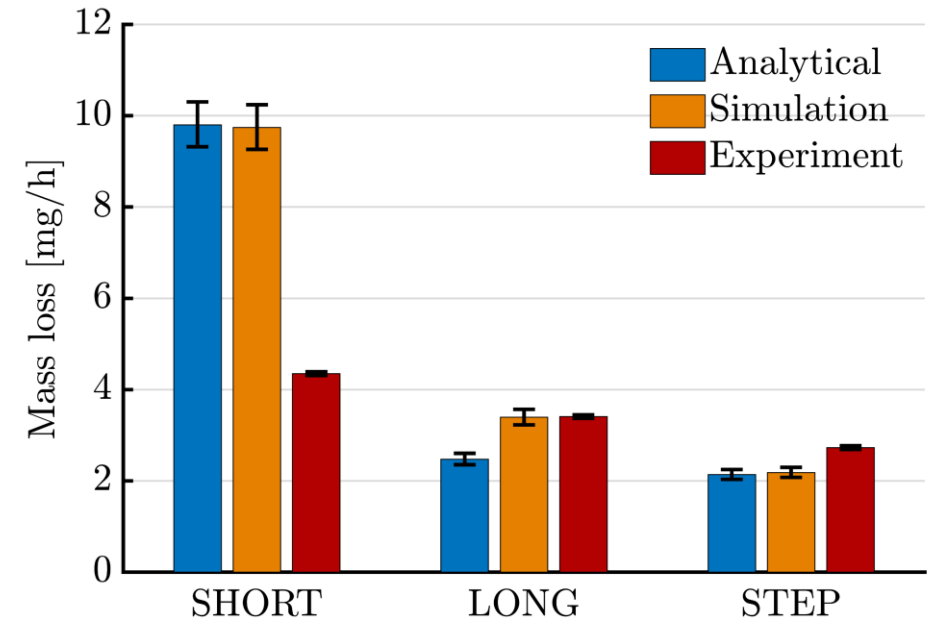
## LONG



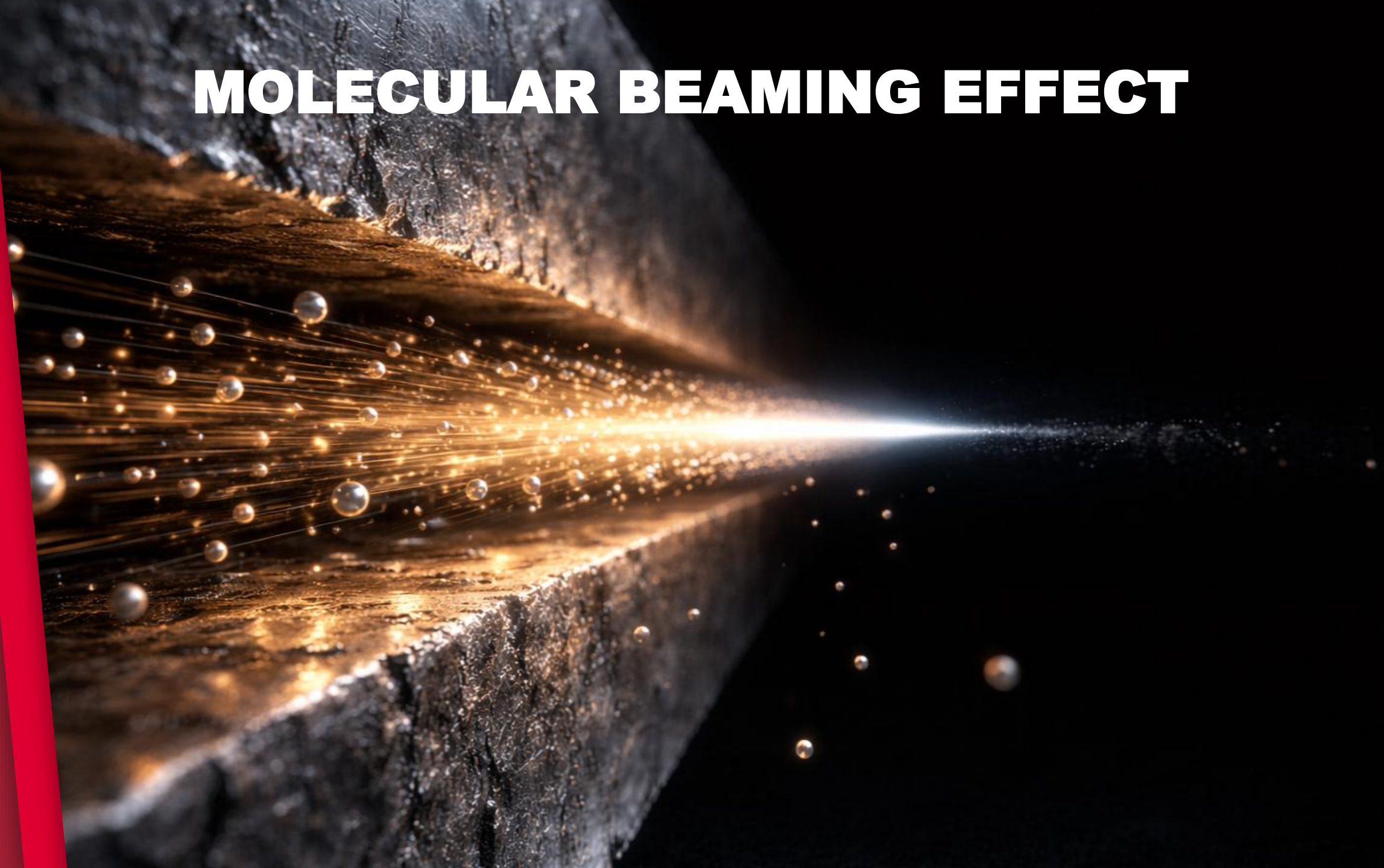
## STEP



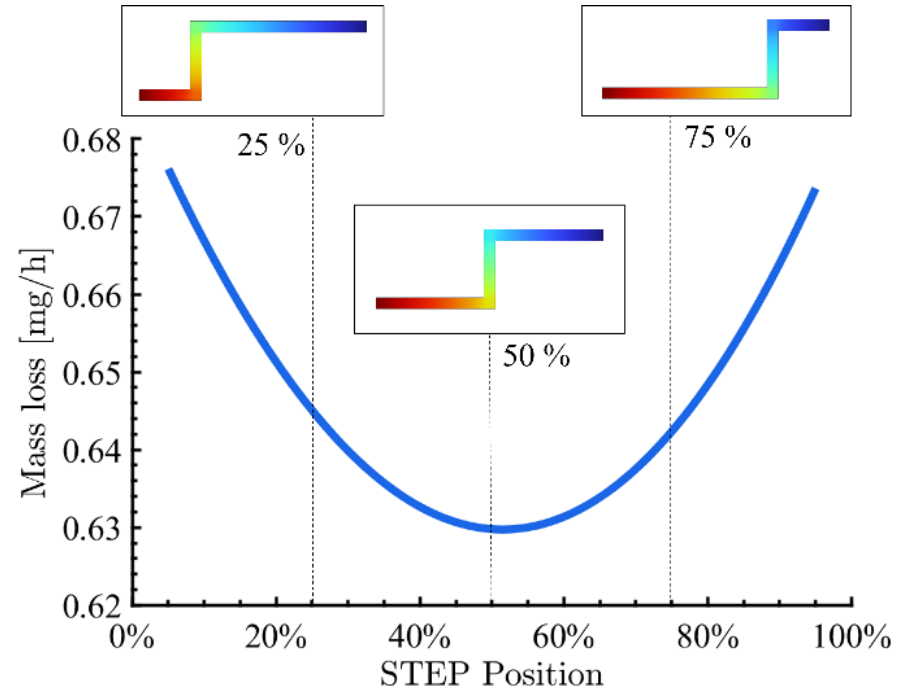
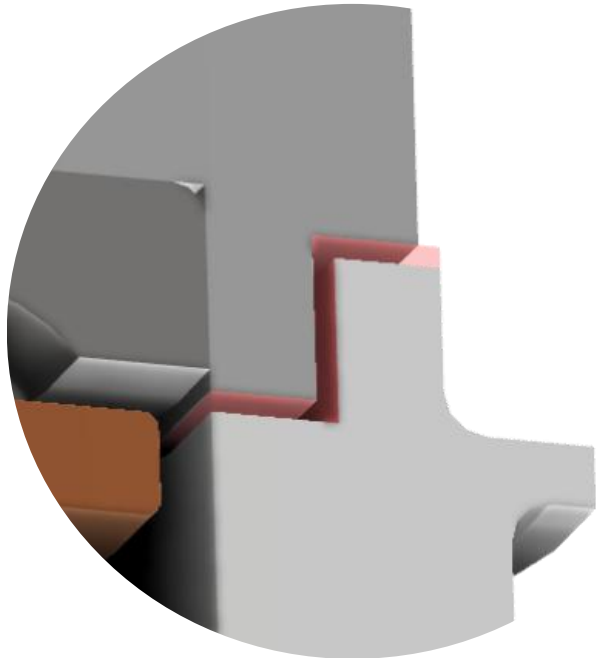
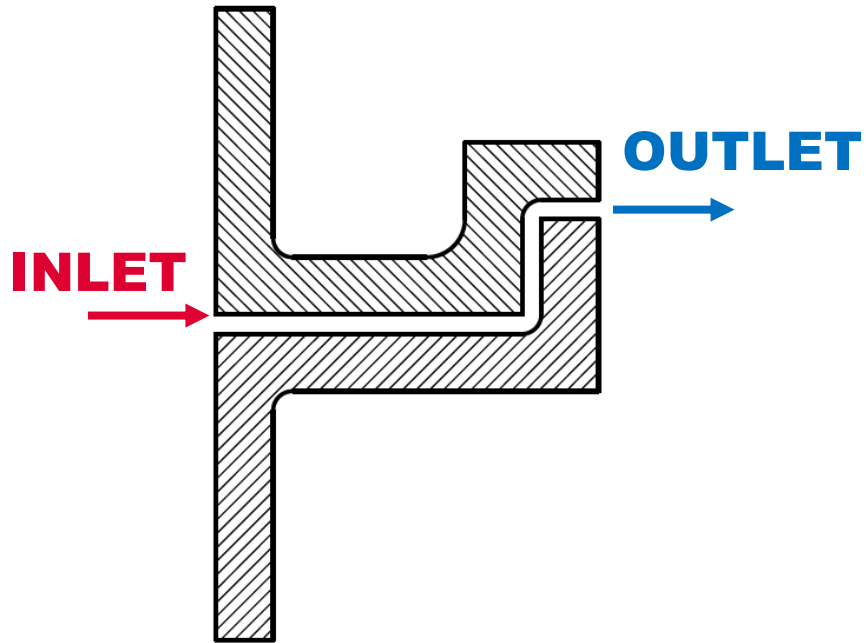
Labyrinth	Width [mm]	Diameter [mm]	Length [mm]
SHORT	$b = 0.5$	$d = 86.5$	$L = 1.5$
LONG	$b = 0.5$	$d = 86.5$	$L = 10$
STEP	$b = 0.5$	$d_1 = 86.5$	$L_1 = 8.25$
		$d_2 = 92.5$	$L_2 = 3.00$
			$L_3 = 1.75$



# MOLECULAR BEAMING EFFECT



**GEOMETRY**



Step position (see Fig. 9)	Mass loss [mg/h]	Loss rate *
10 %	0.665	+ 5.19 %
25 %	0.643	+ 1.62 %
50 %	0.633	-
75 %	0.640	+ 1.24 %
90 %	0.662	+ 4.71 %

# LABYRINTH SEAL OPTIMIZATION

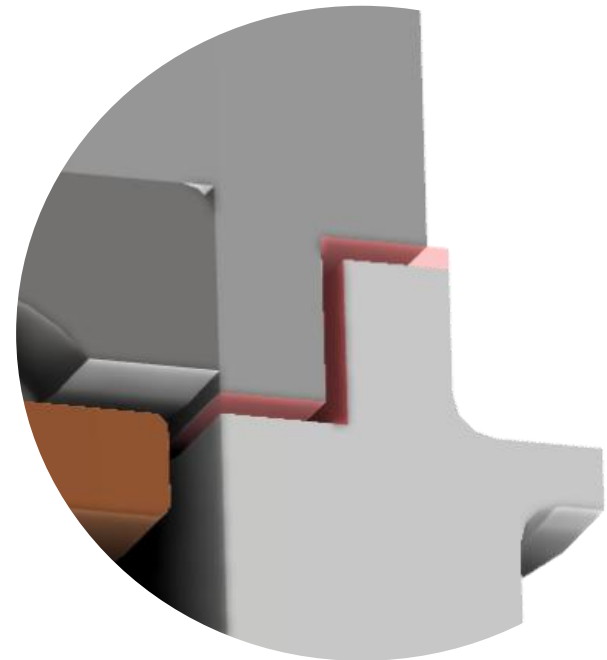
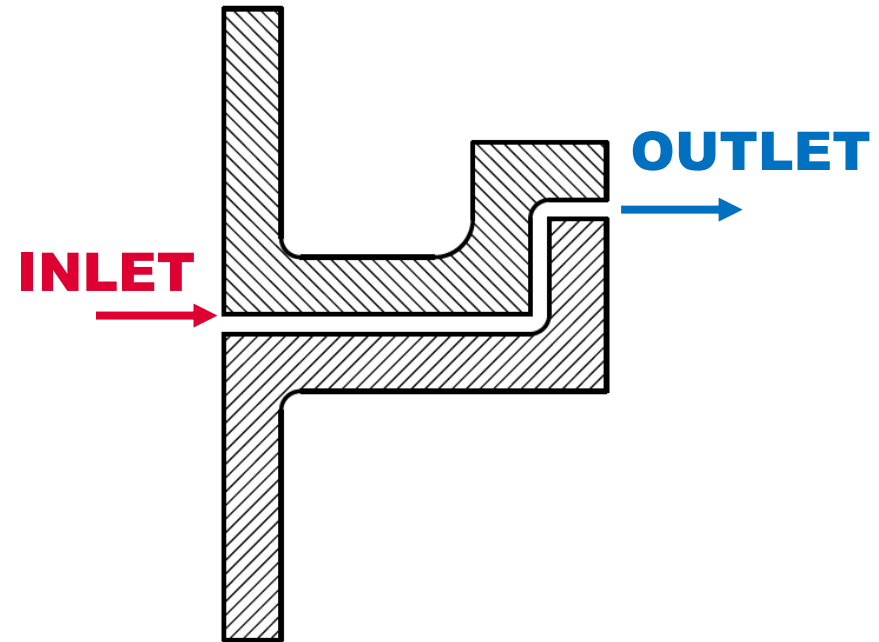
- **Overall geometry**

**Length, Width, Complexity**

- **Geometrical modifications**

- **Surface topography**

- **Rotational influence**



Mass loss [mg/h]

0.68

0.67

0.66

0.65

0.64

0.63

0.62

0

# LABYRINTH SEAL OPTIMIZATION

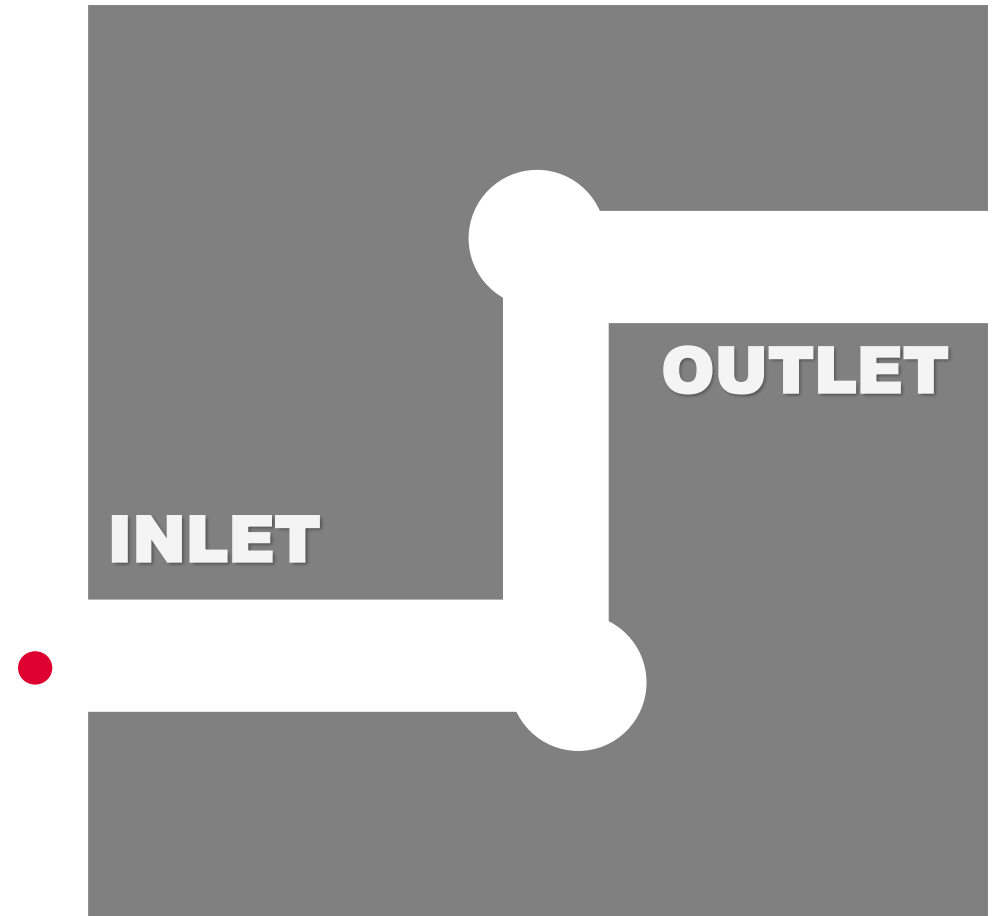
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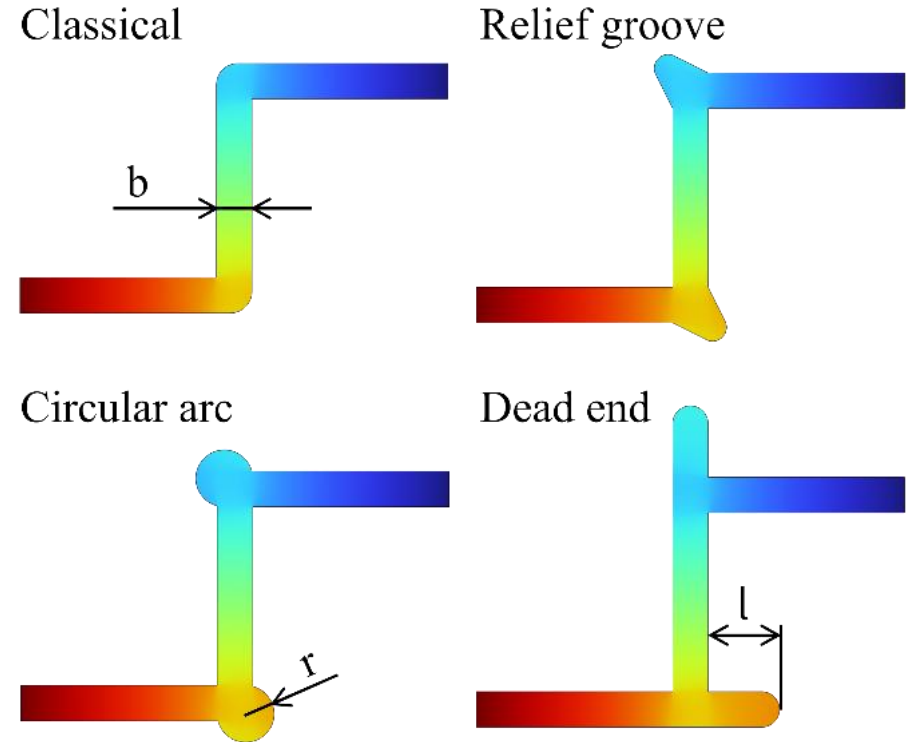
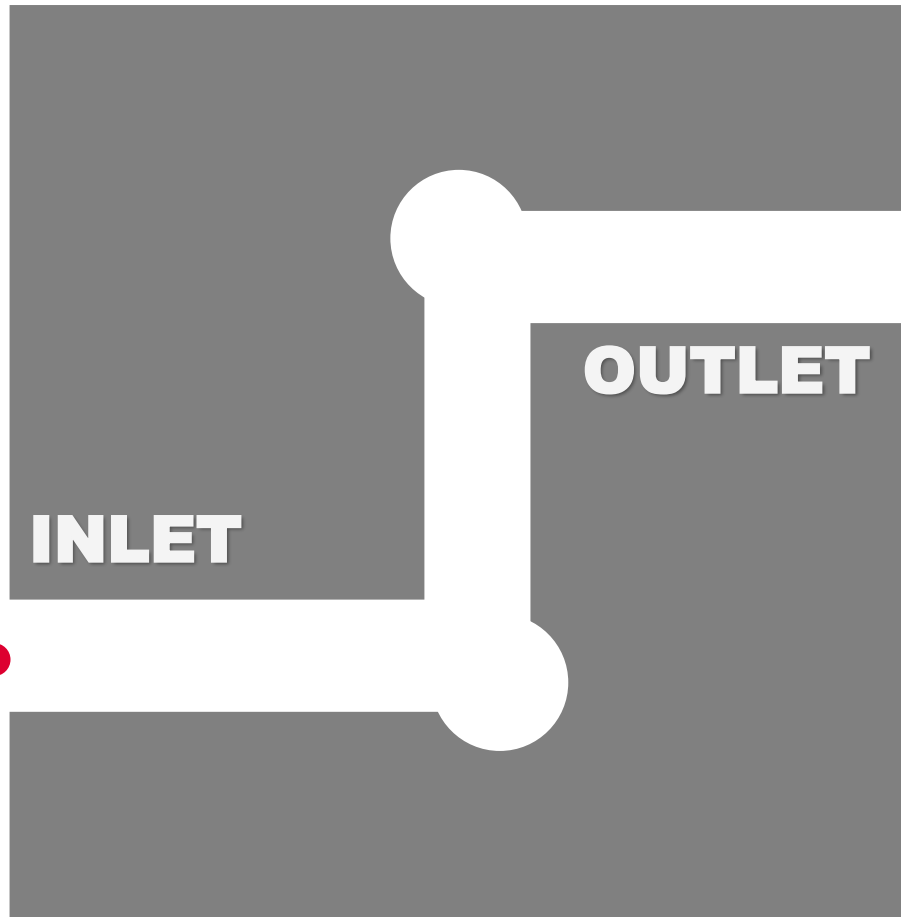
- **Geometrical modifications**

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# MODIFICATIONS



Corner geometry	Characteristic parameter	Loss reduction
Classical	–	–
Circular arc	$r = b$	3.8 %
Relief groove	type G*	3.9 %
Dead end	$l = 2b$	4.3 %

# LABYRINTH SEAL OPTIMIZATION

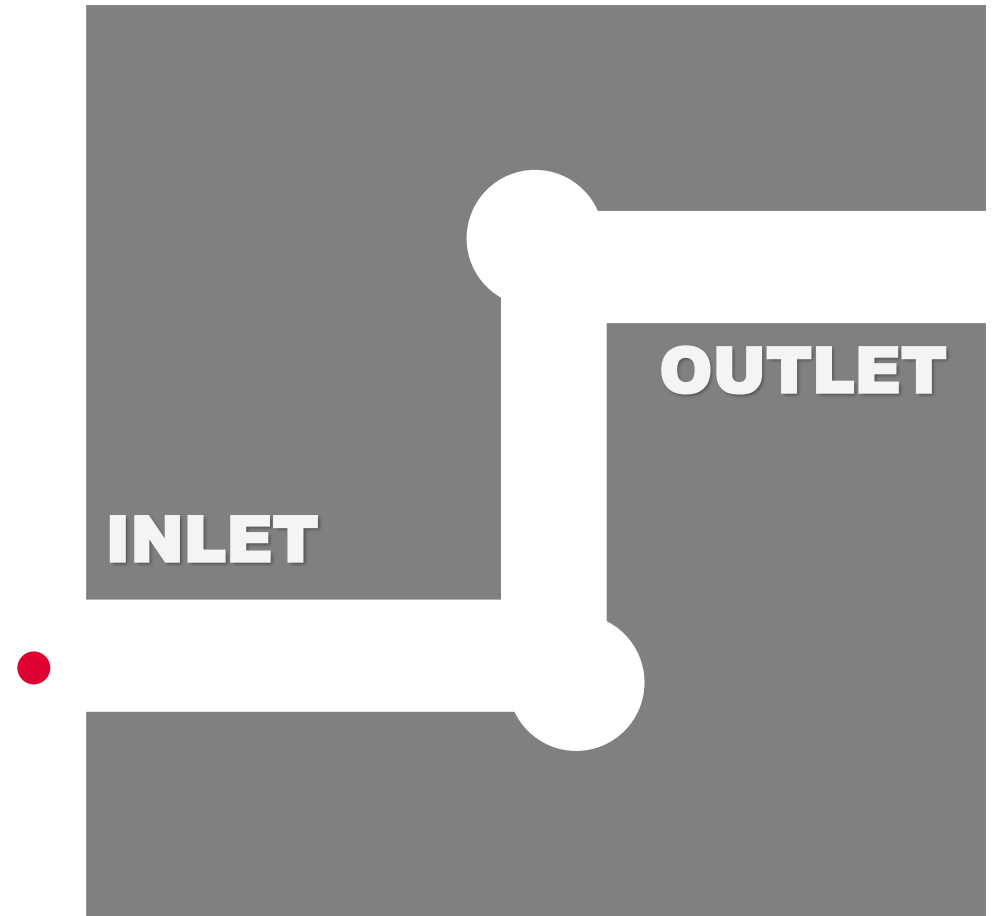
- **Overall geometry**

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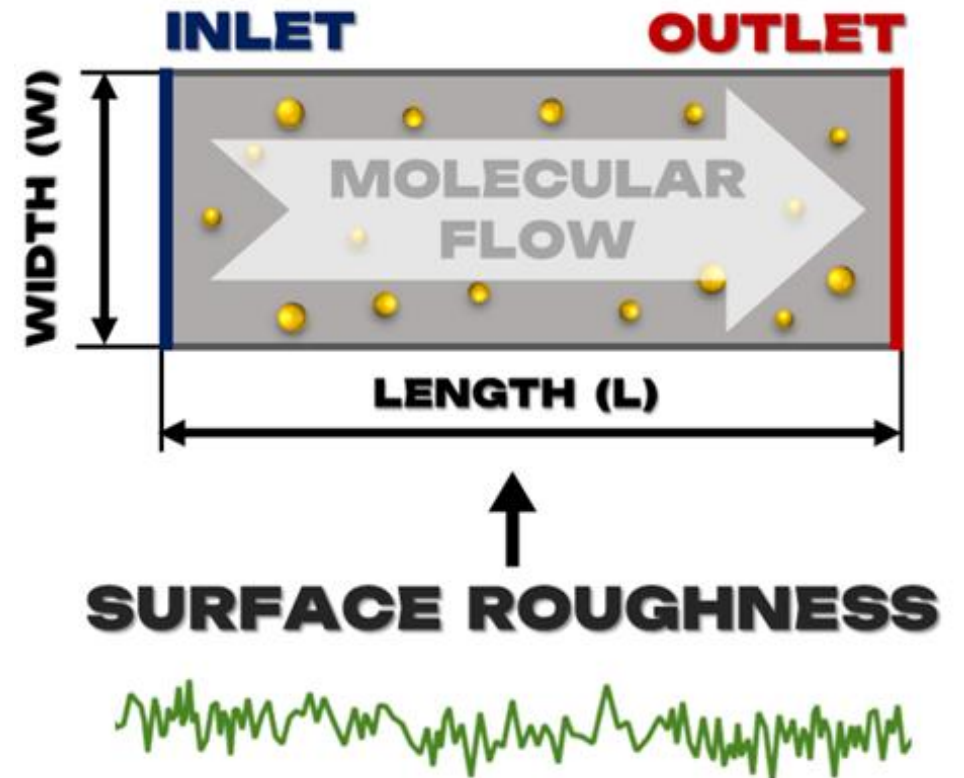
- Overall geometry

Length, Width, Complexity

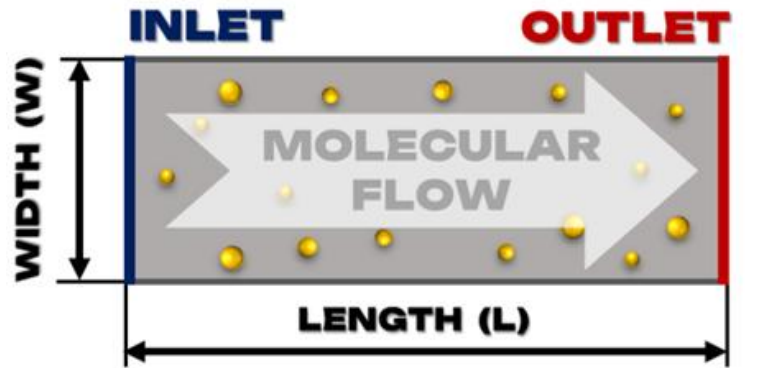
- Geometrical modifications

  - Surface topography

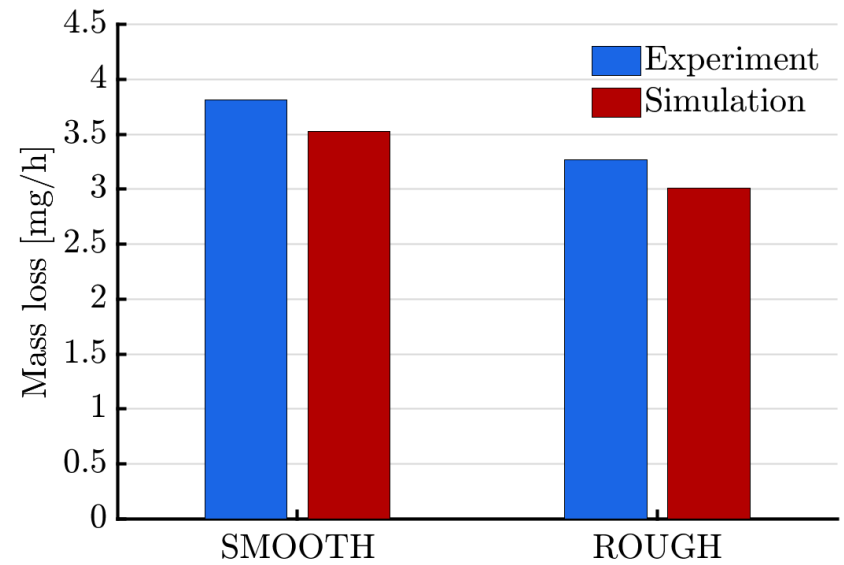
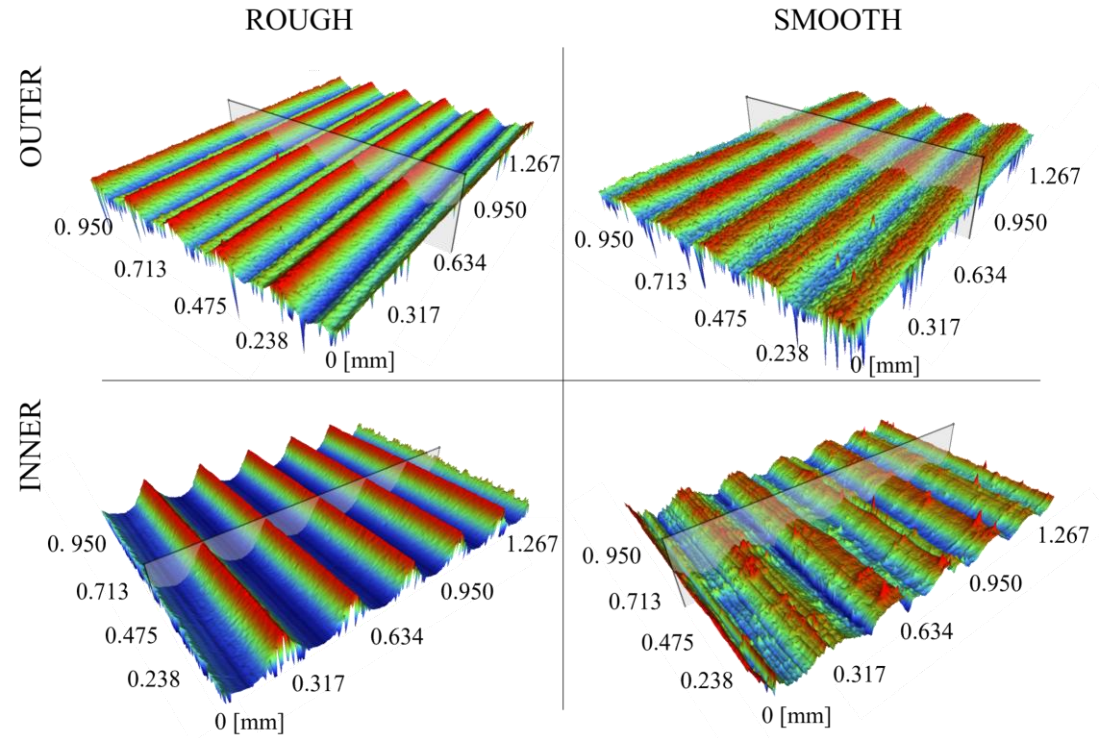
  - Rotational influence



# ROUGHNESS

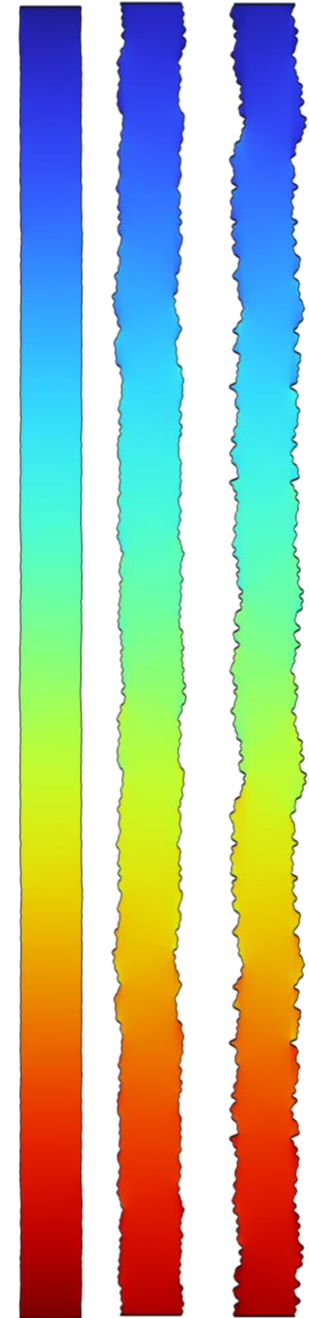
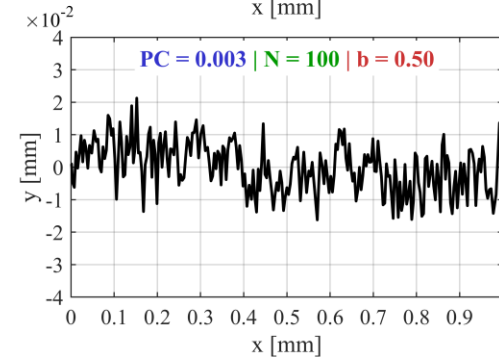
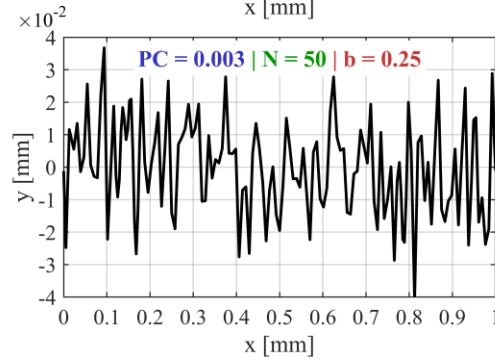
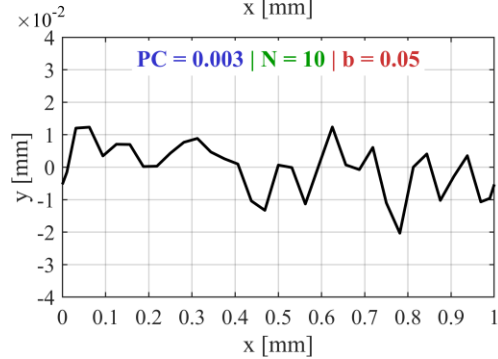
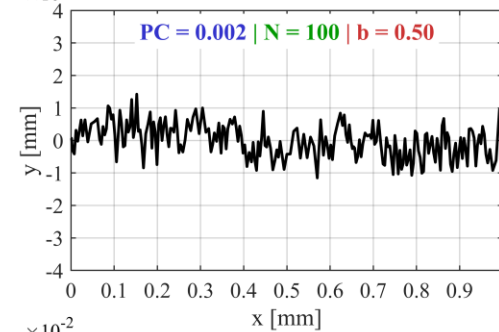
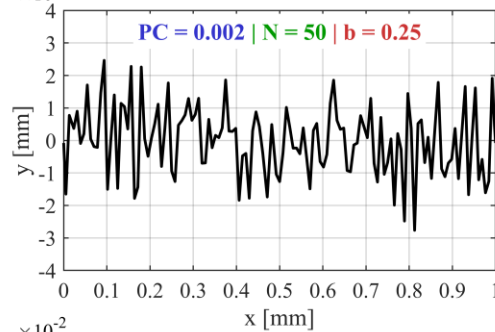
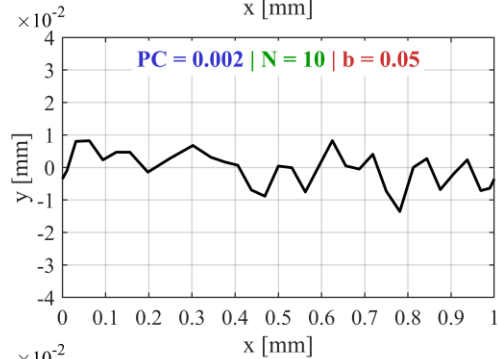
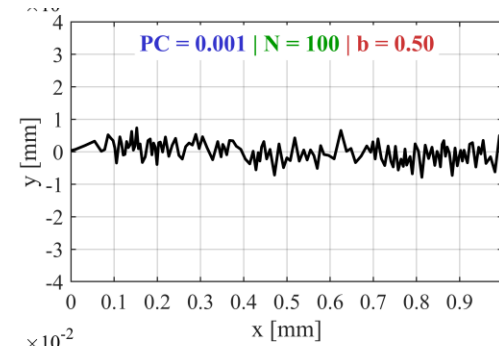
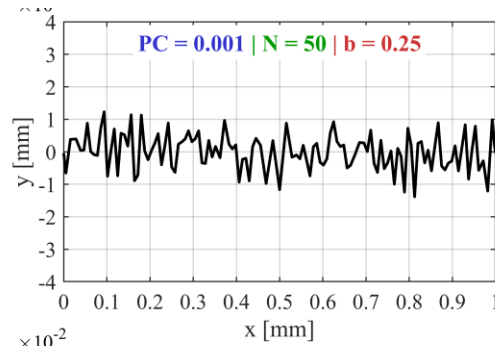
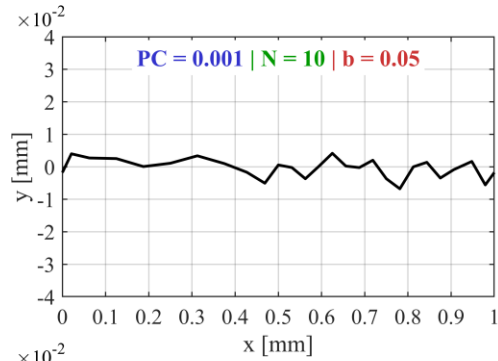


**SURFACE ROUGHNESS**

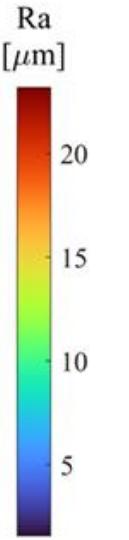
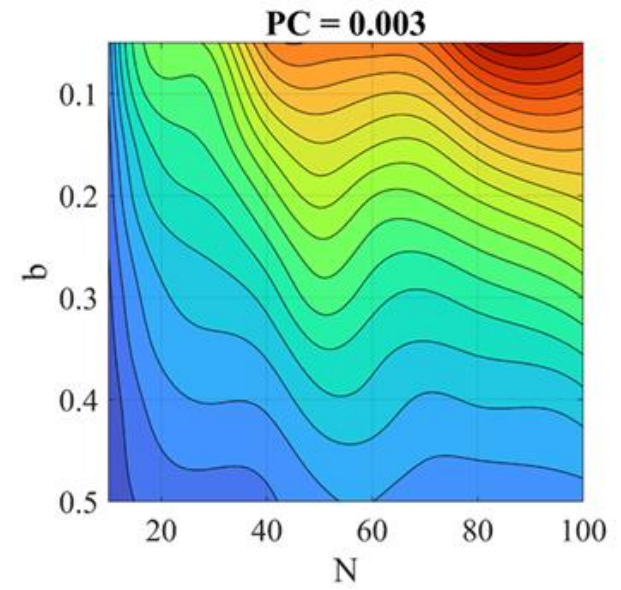
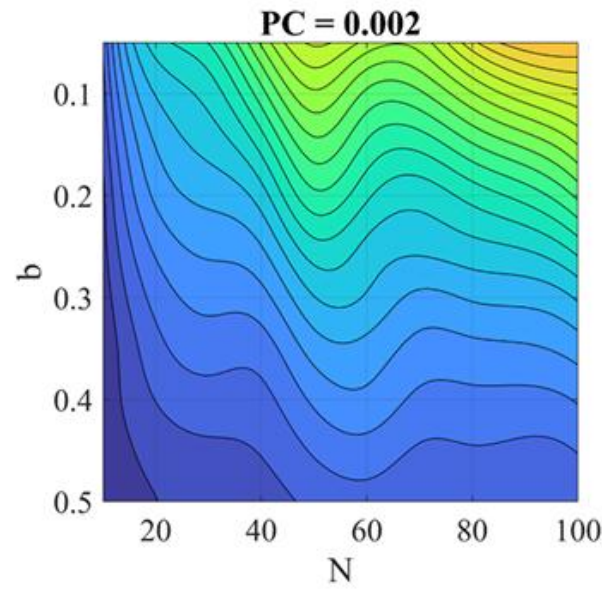
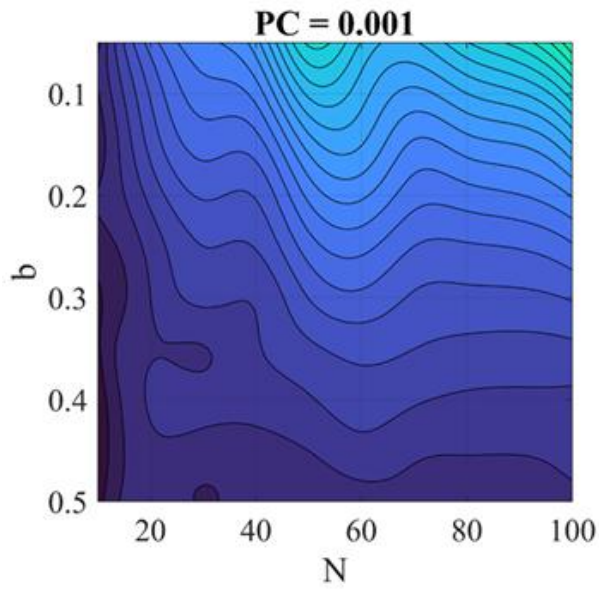
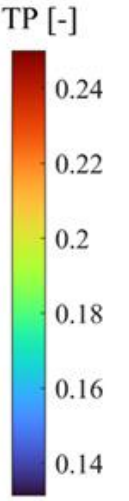
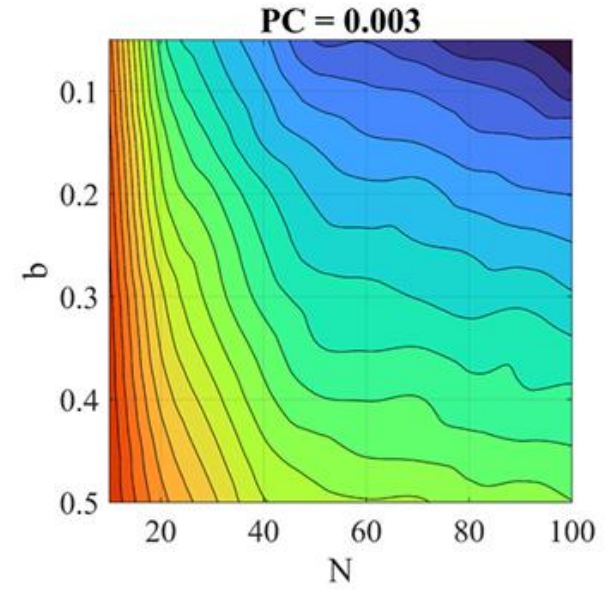
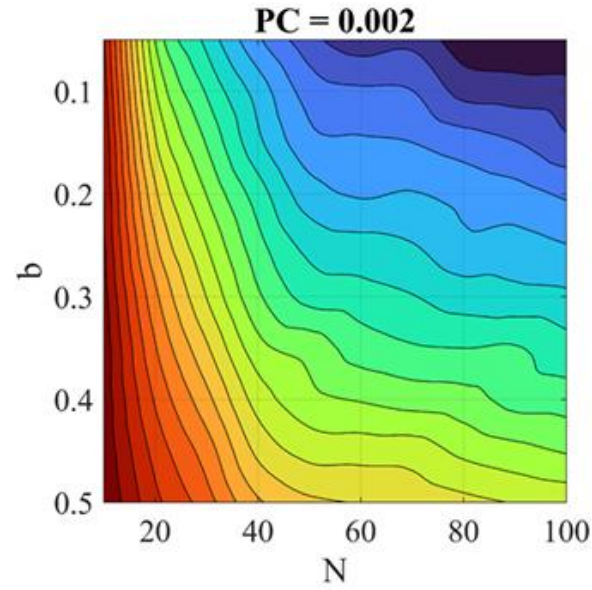
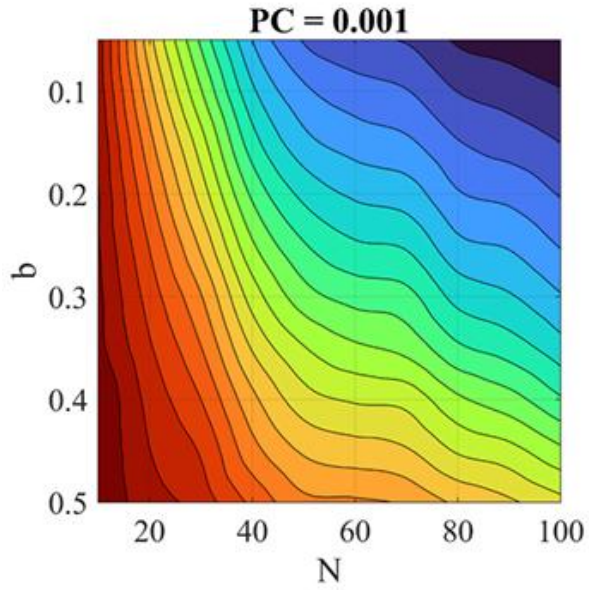


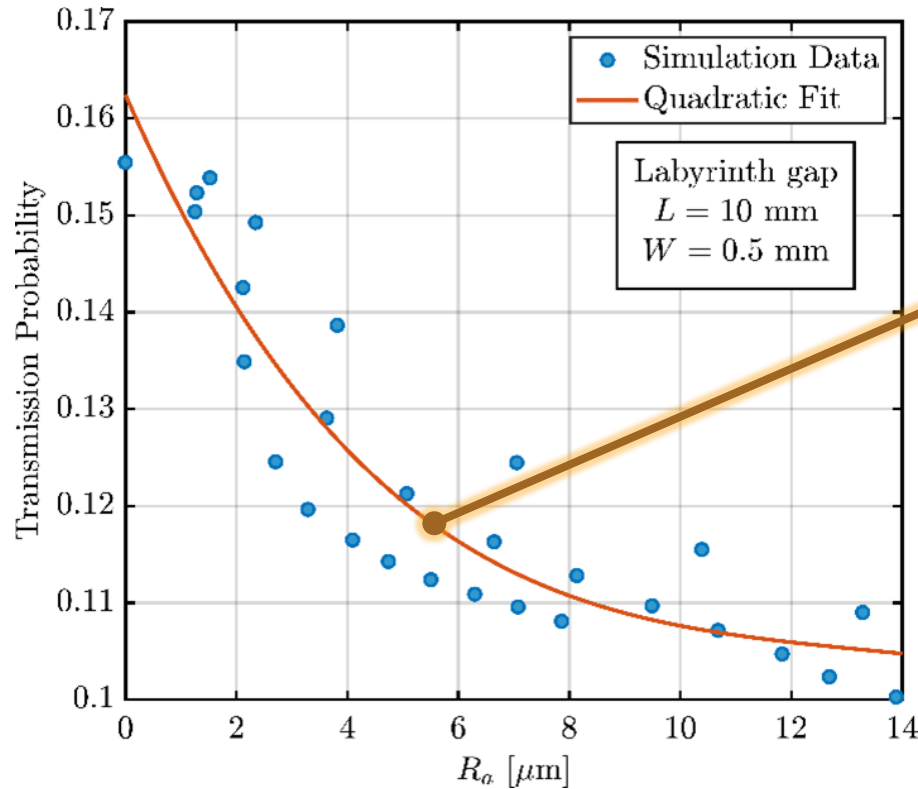
# ROUGHNESS

$$z = PC \bullet \sum_{n=-N}^N (n^2)^{-\frac{b}{2}} \cdot g(n) \bullet \cos(2\pi(nx) + u(n))$$



# ROUGHNESS





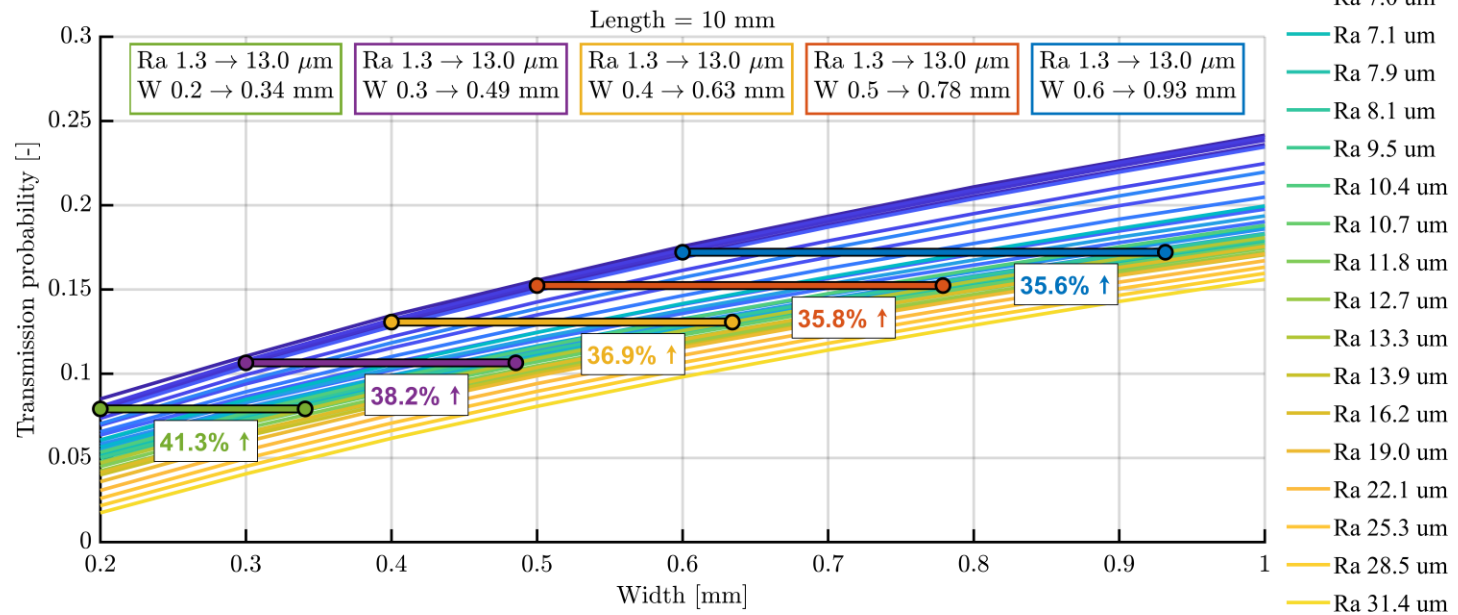
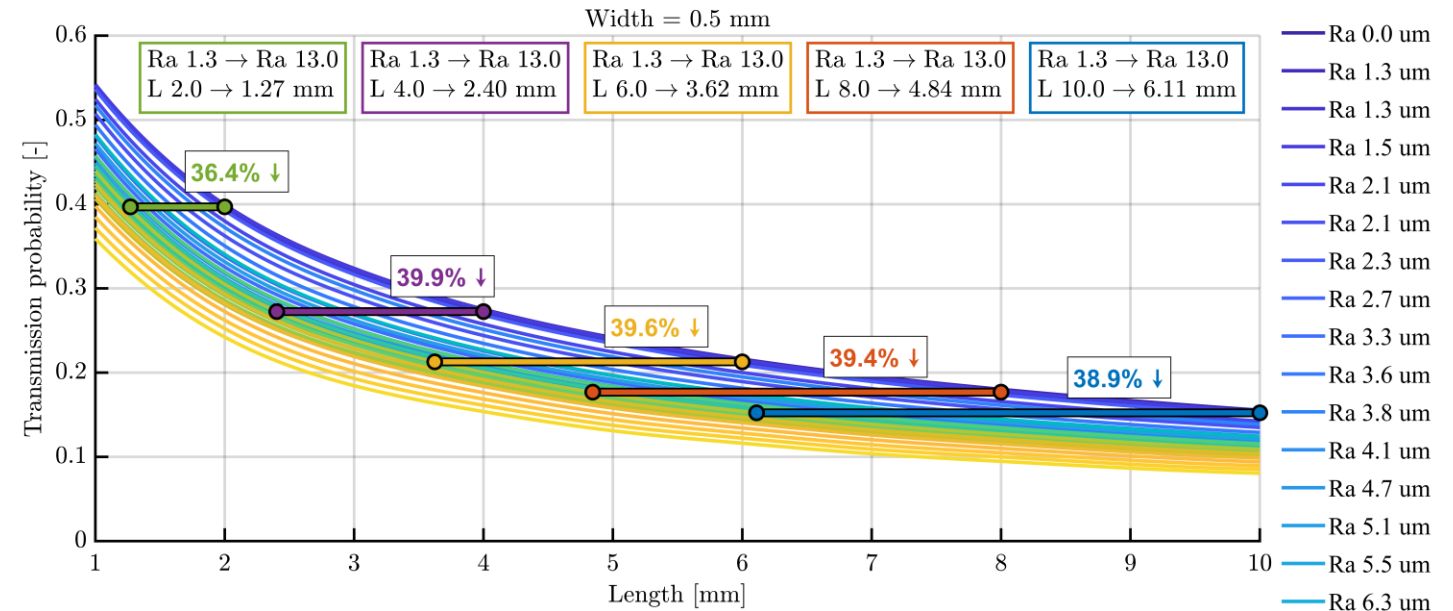
## Transmission probability correction model

$$TP_{corr} = A(W, L) \cdot Ra^2 + B(W, L) \cdot Ra + C(W, L)$$

	SMOOTH	ROUGH	Roughness influence
Experiment	3.8 mg/h	3.3 mg/h	- 13.2 %
Simulation	3.5 mg/h	3.1 mg/h	- 11.4 %

1. Determine the surface roughness  $Ra$
2. Identify the channel dimensions ( $W, L$ )
3. Obtain polynomial coefficients  $A_{W,L}$   $B_{W,L}$   $C_{W,L}$
4. Calculate corrected transmission probability ( $TP_{corr}$ )

# ROUGHNESS



# LABYRINTH SEAL OPTIMIZATION

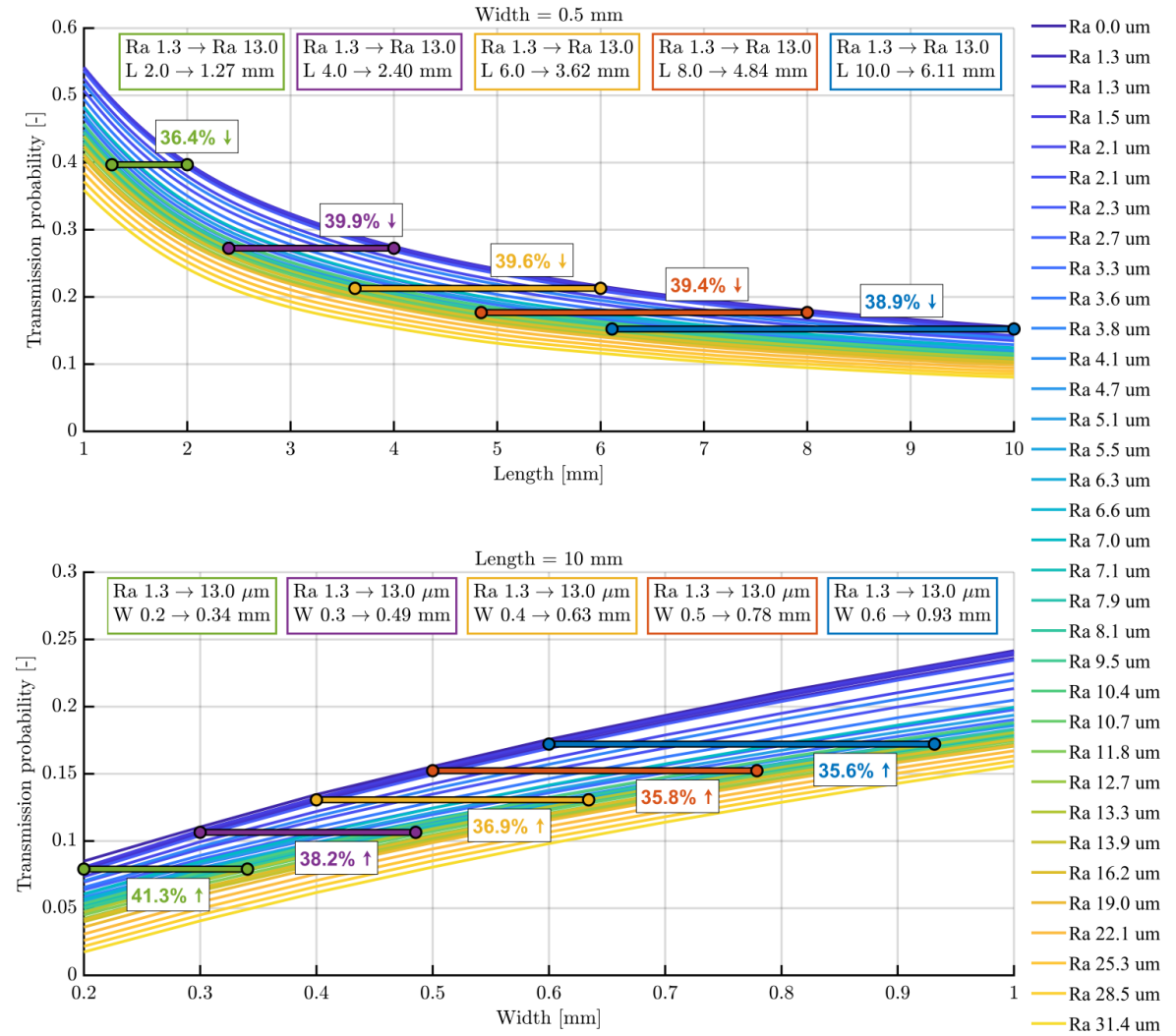
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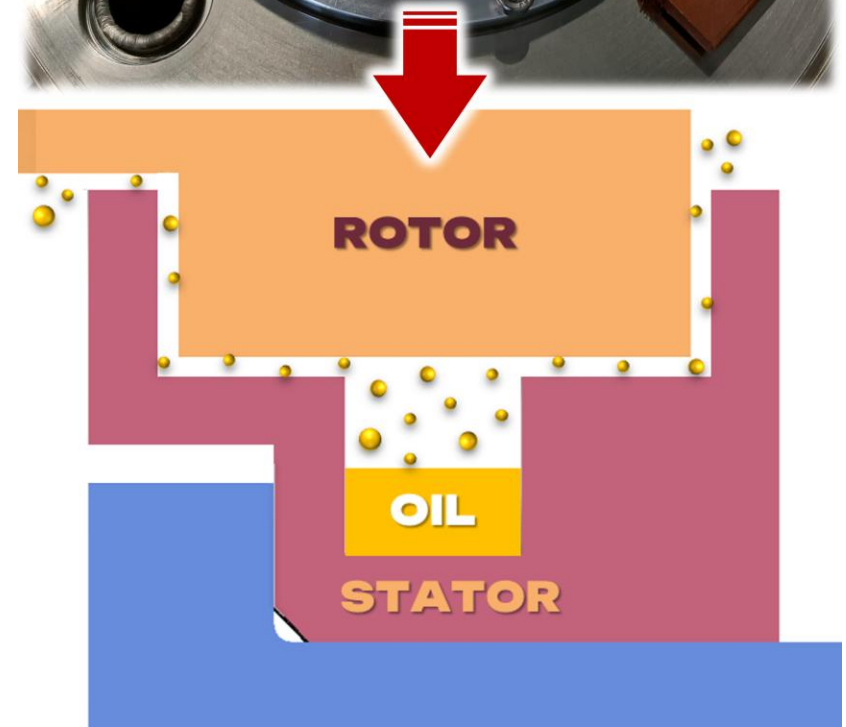
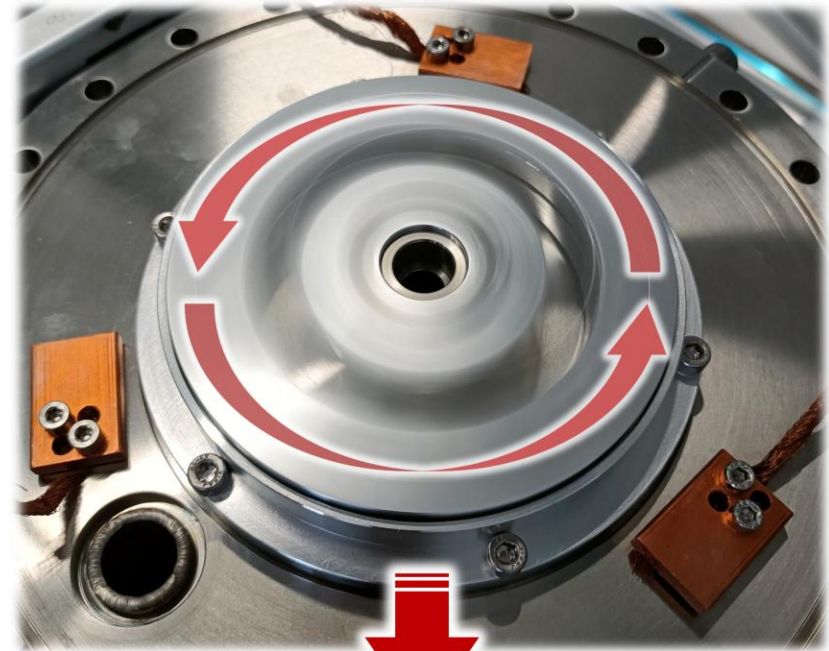
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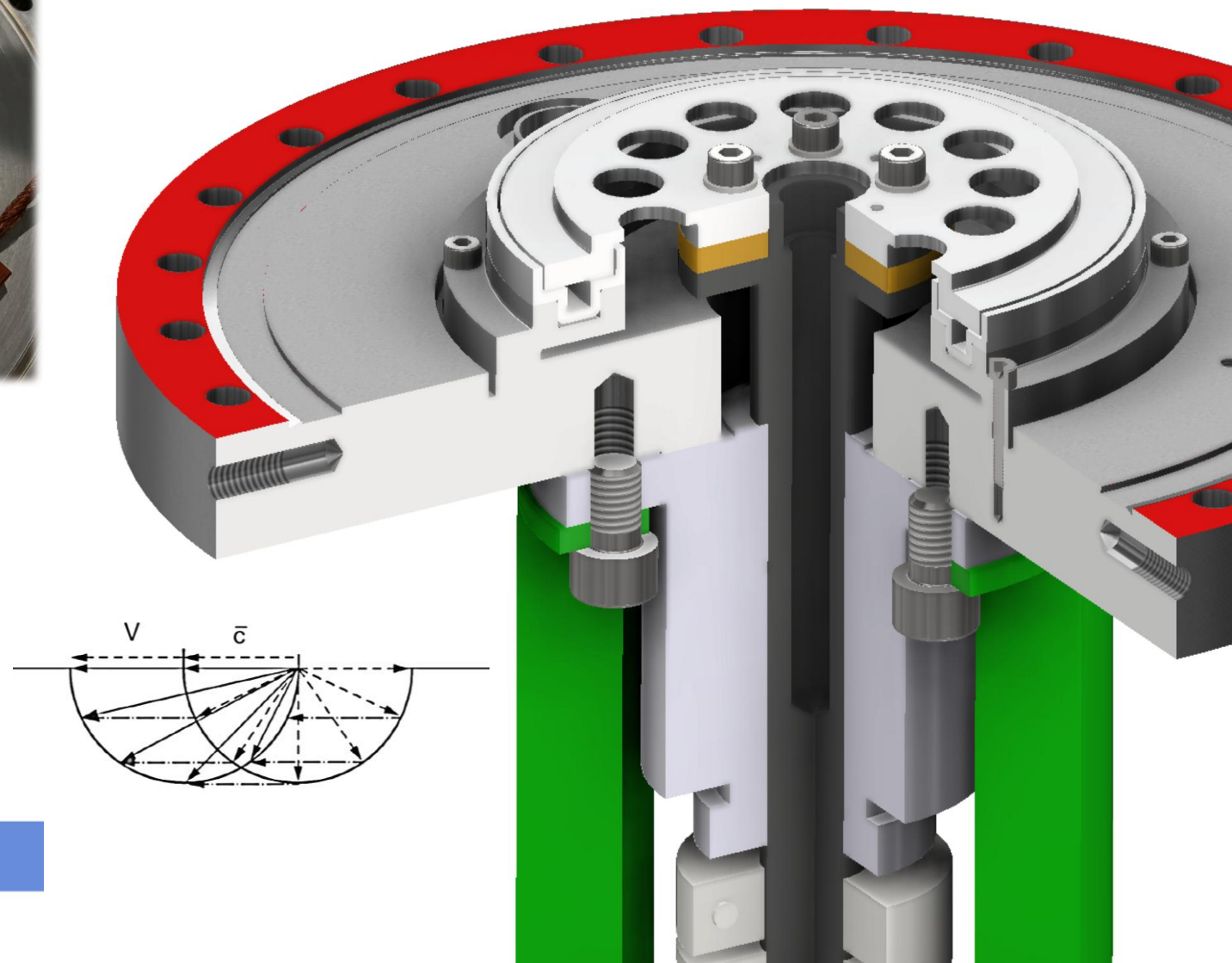
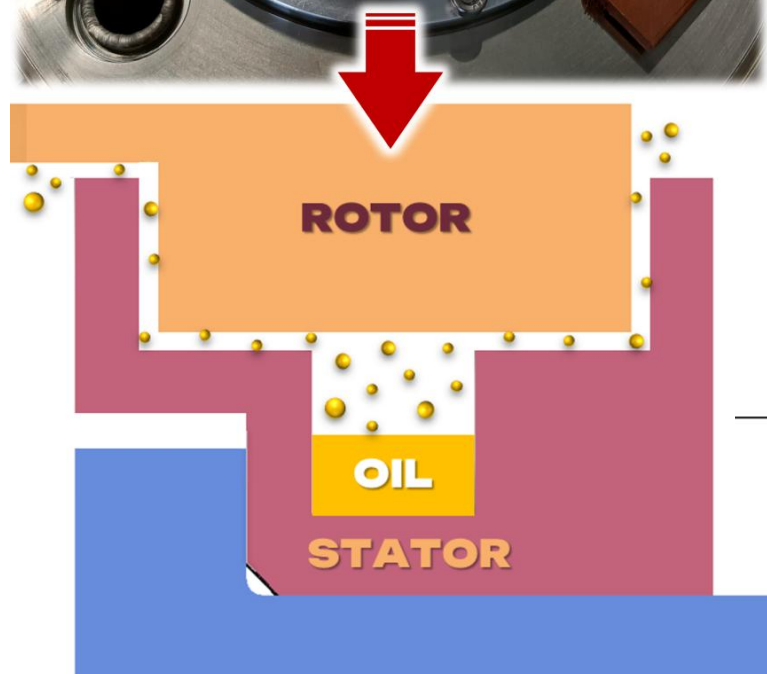
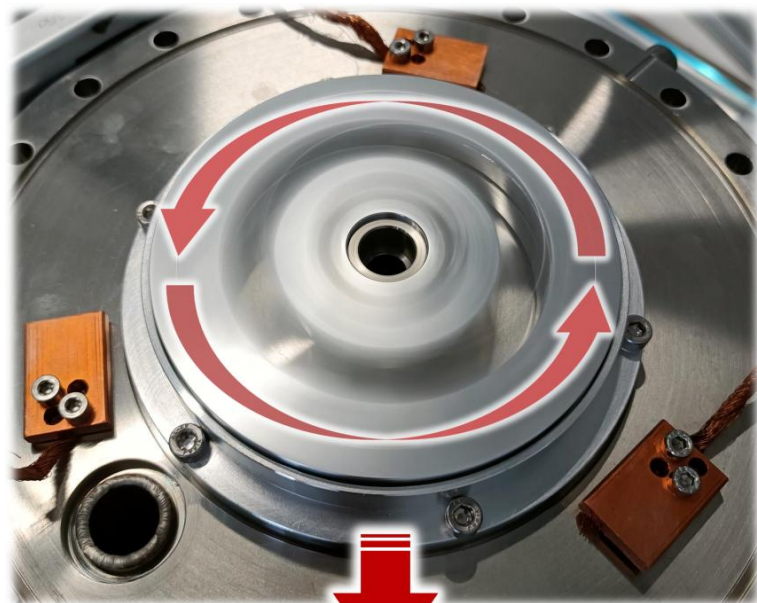
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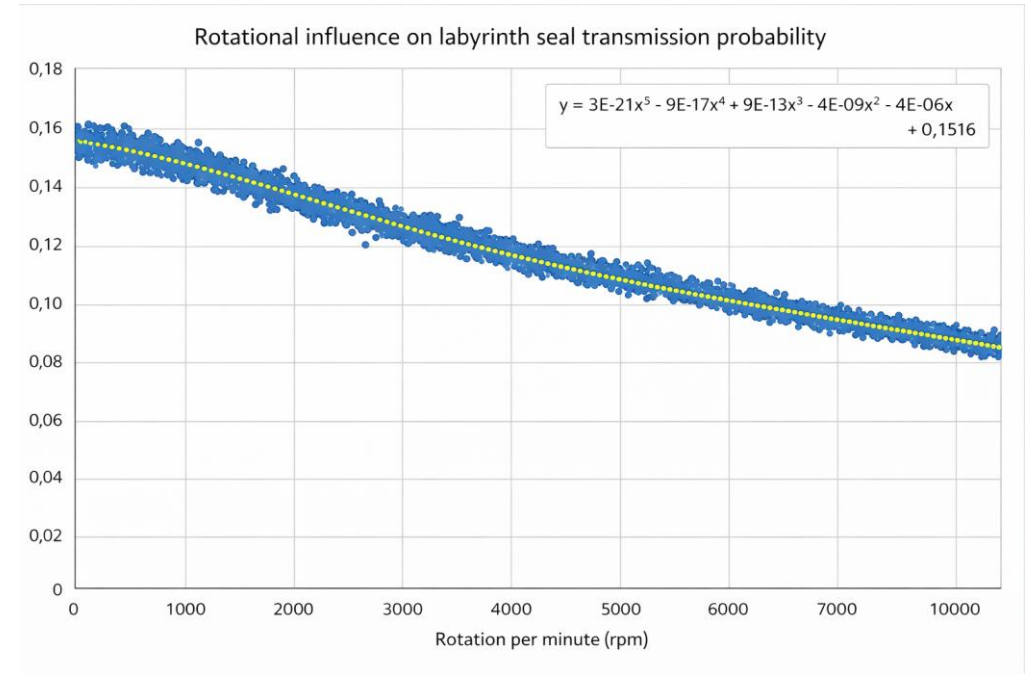
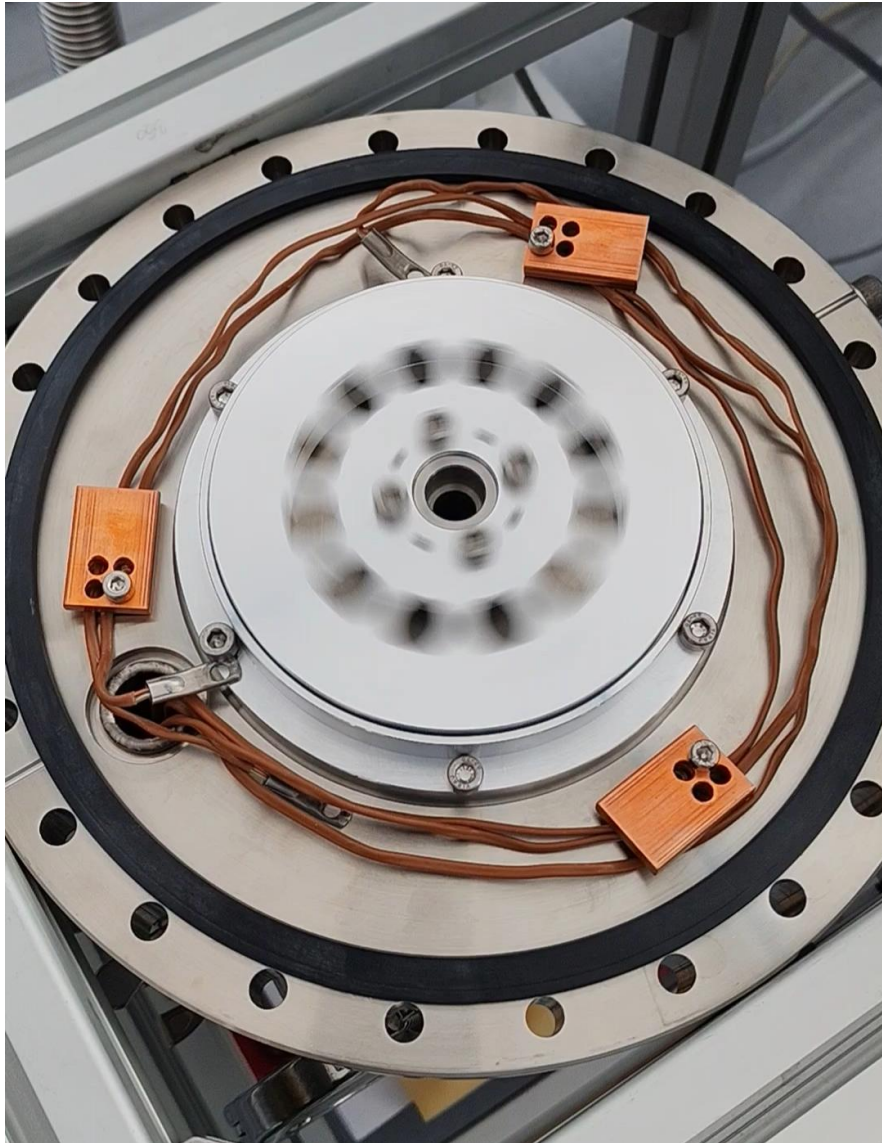
- Rotational influence



# ROTATION



# ROTATION



	0 RPM	2000 RPM	Spin influence
Simulation	0.178 mg/h	0.161 mg/h	- 9.05 %
Experiment	0.188 mg/h	0.168 mg/h	- 10.6 %

# LABYRINTH SEAL OPTIMIZATION

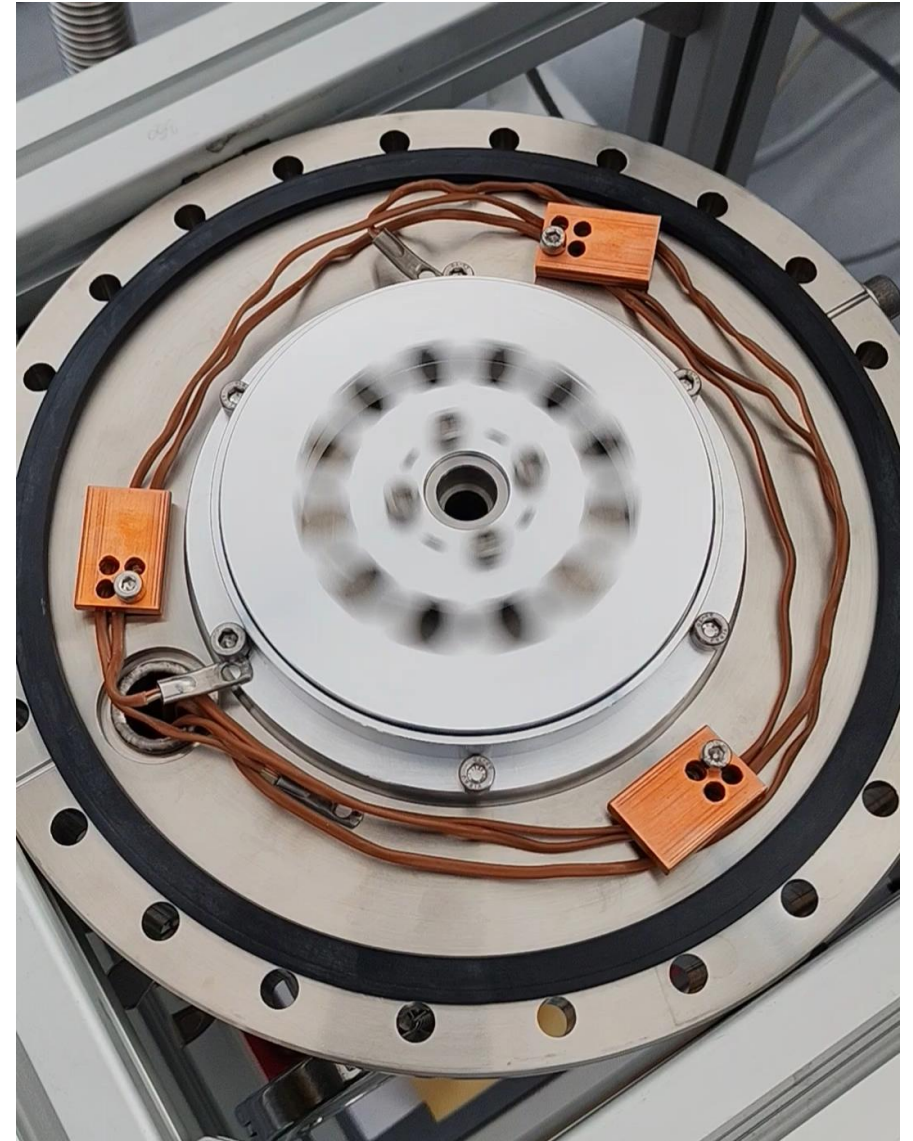
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# CONCLUSION

- **Simulation align with experiments for complex seals**
- **Stepped seals provide best sealing**
- **Molecular beaming increases oil loss**
- **Roughness affects transmission probability**
- **Local modifications boost efficiency**
- **Rotation influences transmission probability**



# PUBLICATIONS

- **POUZAR, J.**, KOSTAL, D., SPERKA, P., KRUPKA, I., HARTL, M. Experimental study of space lubricant evaporation in a high vacuum environment. *Vacuum*, 2024, 219(A), 112758. ISSN 0042-207X. <https://doi.org/10.1016/j.vacuum.2023.112758>
- **POUZAR, J.**, KOSTAL, D., WESTERBERG, L. G., NYBERG, E., KRUPKA, I. Labyrinth seal design for space applications. *Vacuum*, 2025, 232, 113882. ISSN 0042-207X. <https://doi.org/10.1016/j.vacuum.2024.113882>
- **POUZAR, J.**, KOSTAL, D., WESTERBERG, L. G., NYBERG, E., POLACEK, T., JURIK, K., KRUPKA, I. Influence of surface roughness on molecular flow through labyrinth seals for space applications. *Results in Engineering*, 2025, 28, 107905. ISSN 2590-1230. <https://doi.org/10.1016/j.rineng.2025.107905>
- **POUZAR J.**, KOSTAL D., WESTERBERG L.G., KRUPKA I. Labyrinth seal design for enhanced sealing of evaporated lubricant molecules in space mechanisms. 21st European Space Mechanisms and Tribology Symposium (ESMATS), 2025. <https://www.esmats.eu/esmatspapers/pastpapers/pdfs/2025/pouzar.pdf>



# THANK YOU FOR YOUR ATTENTION

**Josef Pouzar**

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